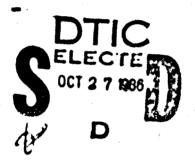
Validation of Aircrew Training Manual Practice Iteration Requirements

John W. Ruffner Anacapa Sciences, Inc.

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Training Research Laboratory

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iterations. These findings are true regardless of a) total career flight hours or b) whether the tasks are psychomotor or procedural. The results (continued)

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also indicate that overall checkride performance can be predicted reliably from performance on a small number of tasks. Additional research is needed to determine the amount of skill decay that occurs for a) no-practice periods longer than 6 months, and b) emergency, instrument, night, and mission-specific tasks not investigated in this research.

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The Fort Rucker Field Unit of the Army Research Institute for the Behavioral and Social Sciences (ARI) has as its primary responsibility the conduct of research and the development of products that serve to increase the effectiveness of Army aviator training—both institutional training and unit training. An important part of this research is to understand the type and amount of training required to sustain the flying skills that aviators initially acquire in the Army Initial Entry Rotary Wing (IERW) course.

This research was designed to make an empirical determination of the minimum of semiannual practice iterations necessary to maintain proficiency on a selected sample of flying tasks. The research was performed in response to a request by the U.S. Army Aviation Center (USAAVNC) Directorate of Evaluation and Standardization (DES).

ELGAR M. JOHNSON

Technical Director

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EXECUTIVE SUMMARY

Requirement:

Because of the high cost of flying hours and the increasing demands on aviators' mission flight skills, a need exists to validate the number of semi-annual task iterations required by the Army Aircrew Training Manuals (ATMs) to maintain individual flying proficiency. The existing requirements were defined by aviation subject matter experts (SMEs) and have not been empirically confirmed. The research reported in this paper was conducted to provide empirical data regarding the minimum number of task iterations required to maintain proficiency in contact and tactical tasks in the UH-1 aircraft over a 6-month test period.

Procedure:

Seventy-nine staff aviators at the U.S. Army Aviation Center (USAAVNC) participated in a 6-month test period in which they flew either zero, two, four, or six iterations of 47 FAC 2 contact and terrain flight tasks in the UH-1 aircraft. Aviators' checkride performance was evaluated at the beginning (Initial Checkride Pretest) and at the end (Final Checkride Posttest) of the test period by standardization instructor pilots (SIPs). The dependent variable was subjects' checkride scores. Independent variables were the number of practice iterations, number of career flight hours, pretest-posttest periods, and ATM tasks. In addition, the reliability of aviators' self-rated confidence to perform checkride tasks to ATM standards was evaluated as a potential predictor of checkride performance.

Findings:

The results indicate that average level of performance in helicopter contact and terrain flight tasks is maintained after 6 months of no-practice. The average level of performance does not significantly improve with as many as six practice iterations. These findings are true regardless of (a) total career flight hours or (b) whether the tasks are psychomotor or procedural. In short, the results do not support the requirement for aviators to perform current semiannual minimum FAC 2 iterations for the majority of ATM contact and terrain flight tasks.

A factor analysis of final checkride data revealed the presence of six independent task dimensions. This finding suggests that a selected set of 10 tasks could be used to predict overall checkride performance with a reliability (R²) of .87. Aviators' self-rated confidence in their ability to perform a task to ATM standards was found to be a nonreliable predictor of actual performance of the tasks.

Additional research is needed to determine the amount of skill decay that occurs for (a) no-practice periods longer than 6 months, and (b) emergency, instrument, night, and mission-specific tasks not investigated in this study.

Utilization of Findings:

The results of this research should be taken into account in implementing changes to the current ATM program. Two specific recommendations are (a) modification of iteration performance requirements, and (b) redirection of evaluation emphasis during checkrides.

VALIDATION OF AIRCREM TRAINING MANUAL PRACTICE STERATION REQUIREMENTS

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INTRODUCTION

PROBLEM

Aircrew Training Manuals (ATMs) are designed to help the aviation unit commander implement and monitor training in his unit and to standardize the individual aviator training program. ATM training is designed to ensure that each aviator achieves and maintains individual flight proficiency. The ATMs contain requirements for the minimum number of task iterations to be accomplished by individual aviators during a six-month period of continuation training. The iteration requirements were defined by a panel of subject matter experts (SMEs). Because the cost of flying hours and the demands on aviators' mission skills continue to increase, a need exists to make an empirical determination of the minimum number of ATM task iterations necessary to maintain individual flying proficiency. The U.S. Army Research Institute (ARI) was requested by the U.S. Army Aviation Center (USAAVNC) Directorate of Evaluation and Standardization (DES) to validate the ATM requirements.

BACKGROUND

Development of the ATMs

With the introduction of the Aviation Career Incentive Act of 1974, Congress and the General Accounting Office established that the Army's flying hour program would be acceptable for funding only if it was fully justified. At that time, the Army was less able than the other services to demonstrate a definitive program of training that carried the aviator through qualification, mission, and continuation training and that identified the specific tasks required in each phase of training. For continuation training, 1 the Army developed a flying hour program requiring 80 hours for each aviator; no satisfactory explanation could be given as to how and for what benefit these hours were being used (Lovejoy & Fresley, 1980).

At the direction of the Vice Chief of Staff of the Army, a special task force from the Army Training and Doctrine Command (TRADOC) was created in late 1976 to develop a flying hour program designed to ensure combat readiness. The initial ATMs were drafted by members of the special task force. The ATMs specified the estimated amount of training required to train individual aviators to an acceptable level of proficiency (qualification and mission training) and to sustain proficiency at that level (continuation training). In addition, the TRADOC task

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The research described in this paper addresses Army ATM continuation training requirements in general, with particular emphasis on training requirements for FAC 2 aviators. The part of continuation training that is designated for Army FAC 2 aviators has also been called "proficiency flying."

force established specific annual training criteria, identified tasks for individual aviators by type of aircraft, defined semiannual training requirements, and related the training requirements to flying hours. The latest version of the ATMs was distributed to the field in FY 81.

The ATMs were developed to help the unit commander fulfill his responsibility for assessing the combat-ready status of the unit, for identifying performance deficiencies of individual aviators, and for developing and implementing the required training program. Although portions of the program are mandated in order to standardize training, the program is sufficiently flexible to enable commanders to tailor training programs to the needs of their unit and the individual aviators within the unit.

ATM Training Requirements

The training requirements that a commander determines to be appropriate for an individual aviator depend on the Aviator Readiness Level (ARL) and Flight Activity Category (FAC) of the aviator. Each aviator is classified into an ARL according to the training status of that individual. Aviators are classified as ARL I only if they have completed mission training and are considered to be combat ready. Aviators are classified into other ARLs if they are a) participating in mission, refresher, or qualification training, b) assigned to a non-operational flying position, or c) restricted from flying for administrative or medical reasons.

Flight Activity Categories (FACs) are classifications of aviator positions. Aviators placed in FAC 2 positions typically occupy "career-broadening" assignments in which flying does not constitute a major part of their job. To minimize the potential deterioration of flight skills during such assignments, FAC 2 aviators are required to fly a minimum amount of hours per calendar period to maintain basic flight skills. The task list for a FAC 2 position consists of all FAC 2 tasks given in the ATMs plus any tactical/special, mission, and additional tasks that the commander designates as supporting Army training readiness goals (Department of the Army, 1981).

Aviators designated as FAC 1 perform combat, combat support, or combat service support missions. FAC 1 aviators are required to be proficient in the tactical tasks appropriate for the type of aircraft flown and for the particular mission of their unit. The commander determines the employment role for each position he designates as FAC 1 and develops a task list for that position. The task list for a FAC 1 position consists of all FAC 2 tasks, plus the FAC 1 tasks and the additional tasks not included in the ATM that the commander considers appropriate.

ARL 1 aviators in FAC 1 and FAC 2 positions are required to complete a minimum number of task iterations and flying hours during a six-month continuation training period. The ATMs specify the conditions under which each task is to be performed and the standards of acceptable performance. Both the iteration and flying hour requirements were analytically formulated by a panel of subject matter experts (SMEs) but were not empirically confirmed. It has been assumed that the number of iterations for each task and flying hour requirements are the minimum necessary to maintain proficiency over a six-month period.

RELEVANT RESEARCH

Task Performance

To develop an approach to validate the ATM iteration requirements for continuation training, literature on the retention of psychomotor and procedural skills was examined. The most frequently cited finding in the retention literature is that procedural skills decay after relatively short intervals of no practice (weeks, months), while psychomotor skills are generally well retained over extended no-practice intervals (months, years) (Mengelkoch, Adams, & Gainer, 1960; Prophet, 1976; Schendel, Shields, & Katz, 1978). Level of original learning is the single most important factor influencing how well psychomotor and procedural skills are retained following a period of no practice. The amount of proficiency loss depends on the length of the no-practice period; however, the absolute rate proficiency loss is approximately the same for individuals of varying initial ability levels (Schendel, Shields, & Katz, 1978).

In addition, several other variables have been found to affect retention; the two most operationally relevant variables are the type of tasks (i.e., psychomotor or procedural) and the activities an individual engages in during the retention interval. It has been shown that these variables often interact to affect retention (Naylor & Briggs, 1961; Gardlin & Sitterley, 1972).

Some research has focused specifically on the retention of flying skills. Although many studies deal with intervals of non-flying that are typically longer than those of concern in the present research, their findings are nonetheless of interest.

Smith and Matheny (1976) examined the level of skill retention among returning Air Force prisoners of war. Subjects' flight hours ranged from 300 to 7000 hours, and time away from flying ranged from 13 months to 102 months. The results indicate that contact flight skills were retained longer and were more quickly relearned than were instrument, procedural, and verbal skills. Aviators with less than 1,000 hours of flight time required significantly more hours to retrain than aviators with more than 1,000 flight hours.

Sitterley and his colleagues (e.g., Sitterley & Berge, 1972) examined the retention of procedural and continuous control skills for periods of one to six months for subjects flying simulated manned spacecraft. Their results indicate that time to execute procedural tasks increased significantly after only a one-month period of no practice. Proficiency on continuous control tasks decreased moderately for the first three months and rapidly from three months to six months.

In a review of literature relevant to Army proficiency flying, Wright (1969) was in agreement with the previously mentioned findings concerning the relative rates of proficiency loss for psychomotor and procedural skills, the importance of amount of initial learning, and the relationship between amount of proficiency loss and the length of the no-practice interval. In addition, he concluded that (a) flight skills are retained well for periods of up to two years, (b) skills that decay

can be retrained quickly, (c) forgetting curves for flight skills are negatively accelerated, and (d) initial retention performance is affected by the similarity of both the original learning task and interpolated tasks to the retention task.

Wright (1973) gathered Army aviators' self-ratings of skill levels achieved during proficiency training and refresher training following periods of nonflying as long as 36 months. His findings indicate that the amount of self-rated skill decrement and the amount of refresher training required are similar for aviators who engaged in proficiency flying and those who did no flying during equal periods. Self-rated basic visual flight skills remained at acceptable proficiency levels for nonflying or proficiency flying periods as long as 36 months; but, for one-half of the aviators in the study, self-rated instrument flight skills fell below acceptable levels within 12 months.

A small-scale study by the Human Resources Research Organization (HumRRO, 1974) obtained instrument flight performance data on aviators who were retrained in the 2B24 helicopter simulator. This simulator is motion-based but is not equipped with an external visual scene. The results indicate that aviators who are in proficiency flying assignments require approximately the same number of simulator training hours to pass an instrument checkride as aviators who are in a nonflying status for periods between 9 and 24 months.

Both the Humrro (1974) study and Wright's (1973) study suggest that proficiency flying programs, as currently exercised, provide little, if any, improvement in training efficiency over a schedule of non-flying that is followed by a program of retraining appropriate to an aviator's next assignment. Data from these studies also suggest that, since the skills that are likely to decay are procedural skills, most of the proficiency maintenance or retraining requirements can be met by using simulators or other training devices that are effective for training and practicing procedural skills.

A recently completed research effort by the ARI Field Unit at USAAVNC provided data that are relevant to the present research. In Phase I of this effort, Allnutt and Everhart (1980) used the UH-1 aircraft to retrain a group of 17 Individual Ready Reserve (IRR) aviators to pass a contact checkride, excluding tactical flight and instrument flight proficiency. Previous experience of the subjects ranged from 400 to 2,500 total flight hours, with a mean of 1,292 hours. Time away from flying ranged from two to nine years, with an average of six years.

The results of Phase I show that an average of about 13 flight training hours are required to retrain the aviators to criterion. Aviators with fewer total military flight hours and more years away from flying required more retraining hours to pass the checkride. The main deficiencies in flying skills observed following the non-flying period are: slow cross-check, inadequate cockpit and emergency procedures, initial over-controlling, and difficulty with emergency maneuvers-particularly autorotations with turn and simulated antitorque failures.

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In Phase II of the effort, additional retraining was conducted after a three- to five-month interval of nonflying. The results of the Phase II initial checkride indicate some decay of both psychomotor skills and procedural skills during the nonflying interval. Aviators' level of proficiency after the period of nonflying was found to be positively correlated with the level of proficiency measured on the final Phase I checkride. An average of 8.5 flight hours was required to retrain aviators to a satisfactory level of proficiency.

Confidence

The majority of studies reviewed deal with the behavioral aspects of flight skill retention. One variable that may influence an aviator's performance following a period of no practice (or of limited practice) of ATM tasks is the aviator's confidence in his or her ability to perform the tasks to standards. This variable has received little attention in the literature on flight skill retention. However, casual observation indicates that a common perception in the aviation community is that an aviator's confidence is related to actual performance on a task.

In a recent study conducted at USAAVNC, Ruffner, Ciley, and Wick (1981) found a significant pretest-to-posttest increase in aviators' confidence to perform five ATM emergency tasks following a training program, without any significant pretest-to-posttest change in measured proficiency. Furthermore, confidence was not found to be correlated with actual performance. The Ruffner et al. (1981) study examined only a small, homogeneous set of ATM tasks and dealt with a relatively small sample size (n=8). A need exists to evaluate the confidence-performance relationship following a period of no practice or limited practice using a larger number of heterogeneous ATM tasks and employing a larger sample size.

Conclusions From Previous Research

A review of the literature suggests the following broad conclusions. Both psychomotor skills and procedural skills are retained to some degree after periods of nonflying and both can be relearned. However, psychomotor skills are retained better than procedural skills. Second, retention of procedural and psychomotor flying skills depends upon the level of original learning and previous experience. Third, the effects of the type of task involved and the length of the retention interval are highly specific and are likely to interact to affect retention. Finally, it is important to control/have knowledge of the type of events that occur during the retention interval in order to determine the effects of potentially interfering variables on retention.

PURPOSE AND SCOPE

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The purpose of this project is to investigate the task iterations required to maintain flight proficiency in FAC 2 tasks for ARL 1 aviators. Flying hours alone are not an adequate basis upon which to define the amount of practice needed to maintain flight proficiency. For example, much flying time can be expended enroute from a base field to a stagefield with little or no practice of ATM tasks. For this reason, it is essential that proficiency maintenance requirements be defined in terms of practice iterations rather than flying hours.

There are three reasons why a full-scale evaluation of ATM task iteration requirements for all Army aircraft is not a cost effective approach for meeting the research objectives. First, there are a number of common task requirements for many of the Army's rotary wing aircraft. This commonality of tasks should permit a <u>limited</u> amount of generalization of results from one aircraft to another since all rotary wing flight tasks likely draw upon some common underlying skills.

Second, the cost of collecting inflight data using different Army aircraft is directly affected by the relative cost of operating each aircraft. At Fort Rucker, for example, the operating costs for the UH-1 aircraft are approximately twice the operating costs for the OH-58 aircraft, 50% of the costs for the AH-1 aircraft, and 25% of the costs for the CH-47 aircraft. Thus, cost considerations weigh heavily against the use of all aircraft.

Finally, most minimum proficiency flying currently is accomplished in the UH-1, with a lesser amount in the OH-58. The AH-1 and the CH-47 aircraft typically are flown in support of mission requirements and are seldom flown for minimum proficiency maintenance; rather, they are flown by aviators whose primary job is flying these aircraft. Maintenance of proficiency for these aviators is accomplished through continuation training in the systems/mission equipment.

The majority of FAC 2 aviators at USAAVNC and in Forces Command (FORSCON) units use the UH-1 for proficiency maintenance. Use of this aircraft enables the results to be more directly applicable to the largest number of aviators. Therefore, the UH-1 was judged to be the most appropriate aircraft for use in research on ATM proficiency maintenance.

The research reported in this paper was undertaken as the first step in an iterative process of validation. This study is designed to systematically evaluate the FAC 2 task iteration requirements for the UH-1 aircraft. Baseline data are provided on aviator performance in the UH-1 aircraft in a six-month period of controlled amounts of flying. In addition, the relationship between aviators' confidence to perform tasks and actual performance is evaluated.

RESEARCH OBJECTIVES

The specific objectives of the research are the following:

- to determine if the minimum number of semiannual task iterations specified in the ATMs are appropriate for the maintenance of individual aviator proficiency in FAC 2 tasks,
- e to identify the tasks for which changes in the iteration requirements need to be made to better achieve training effectiveness.
- e to determine if previous rotary wing experience (flying hours) is related to proficiency maintenance, and
- e to determine if self-rated confidence is a reliable predictor of actual flight performance.

METHOD

CONSIDERATIONS AFFECTING RESEARCH APPROACH

Two major constraints on conducting research in field units were considered in formulating an approach that addresses the research objectives in a cost-affective and timely manner. The constraints stem from the difficulty of scheduling practice and collecting data in field units.

Scheduling of Practice

Because of the requirement to maintain a combat-ready posture, it is difficult to arrange for aviators in the field to receive less than the currently required number of iterations and flying hours without adversely affecting unit readiness. It is also difficult to control the number of times each ATM task is practiced, the conditions under which it is practiced, and when it is practiced during the six-month training period.

For example, certain ATM tasks (e.g., takeoffs, straight and level flight, hovering) are essential to flying the aircraft and are practiced on every flight. Because of this, aviators complete far more than the minimum number of required iterations on these flight-essential tasks. Even if another aviator in the aircraft performs these tasks, some practice effect is likely for the aviator who is a passive passenger.

Data Collection

A review of current documents and recordkeeping practices suggests that relying on already existing data and recordkeeping practices in the field does not provide sufficient or reliable data upon which to base a validation effort. Specifically, only the minimum number of task iterations required to meet ATM standards currently are recorded in field units. Data on tasks performed in excess of the minimums are not captured for later analysis.

Performance is assessed formally by a grade of "S" or "U" (satisfactory/unsatisfactory) on two occasions: once during the commander's evaluation checkride and again during the hands-on portion of each Annual Aviator Proticiency and Readiness Test (AAPART). Performance data are not gathered frequently enough or in sufficient objective detail to provide the basis for a validation effort. Altering recordkeeping practices in the field was considered to be unfeasible. Furthermore, it is difficult to control for differences among evaluators in remote locations.

In summary, constraints on the scheduling and control of practice and on data collection in field units strongly suggest that the initial phase of the ATM validation research be conducted by utilizing a sample of aviators and a research environment that allow a greater degree of control than is possible in field units.

SUBJECTS

The subjects were selected from FAC 2 aviators assigned to staff positions at Fort Rucker. Staff aviators typically have served in one or two aviation flying positions preceding their assignment to USAAVNC and do not engage in flying activities as a regular part of their current assignment. Therefore, these individuals are good examples of aviators who are required to fly minimum iterations and hours in order to maintain flight proficiency during continuation training. Furthermore, the iteration and flying hour requirements found to be appropriate for FAC 2 aviators extend directly to FAC 1 aviators who also must maintain proficiency in FAC 2 tasks.

Aviators were selected as potential subjects if they met the following criteria: (a) scheduled to be stationed at USAAVNC through project completion, (b) not required to fly as part of their duty assignments, (c) not required to fly a minimum amount of time each month in order to qualify for flight pay, and (d) had less than 750 hours of IP time or fixed wing aircraft time.

The total number of rotary wing flight hours for the aviators who were available to participate in the research was obtained from the information copy of DA Form 759, Individual Flight Record and Flight Certificate. Of the pool of aviators meeting the above criteria, the 84 aviators with the lowest number of rotary wing flight hours were chosen as subjects. All subjects were male. Subjects were current in the UH-1 aircraft. In addition, some subjects were qualified in other rotary wing aircraft. Although it was not possible to control experimentally for previous experience, an attempt was made to obtain subjects with a sufficient range of career flight hours to permit generalization of results to other aviators.

Subjects completed a demographic questionnaire to provide additional relevant information such as age, time since flight school graduation, time at Fort Rucker, aircraft qualifications, rotary wing flight hours, fixed wing flight hours, and simulator hours. The questionnaire is included in Appendix A. Major demographic characteristics of the subjects are summarized in Table 1. Flight hour data included in the table are taken from DA Form 759 for the period prior to 1 June 1982. Total flight hours ranged from 304 to 2,874 hours. Because the distributions of flight hour data were positively skewed, the median is presented as an alternate representative measure of central tendency.

A stratified random sampling procedure was used to assign the subjects to one of seven groups. The number of rotary wing flight hours was the basis of stratification. The subject groups are summarized in Figure 1.

TABLE 1
SUMMARY OF DEMOGRAPHIC DATA

VARIABLE	MEDIAN	MEAN	SD
AGE	33.06	33,22	3.33
MONTHS SINCE FLIGHT SCHOOL GRADUATION	93.50	90.18	45.21
MONTHS SINCE ASSIGNED TO FORT RUCKER	13.70	14.04	8.62
TOTAL ROTARY WING (RW) FLIGHT HOURS	915.00	1080.25	610.48
RW HOURS LAST 12 MONTHS	42.93	57.06	56.75
RW HOURS LAST 6 MONTHS	21.10	23.54	17.23
TOTAL RW SIMULATOR HOURS	107.25	108.92	35.69
SIMULATOR HOURS LAST 12 MONTHS	19.80	19.70	9.14

Subjects in Group 1, the control group, did not fly during the six months between the initial and final checkride. Subjects assigned to Group 2 were scheduled to complete two iterations of each task approximately four months (during Practice Period I) prior to the final checkride. Subjects assigned to Group 3 were scheduled to complete two iterations approximately two months (during Practice Period II) prior to the final checkride. Subjects assigned to Groups 4 and 5 were scheduled to complete four iterations during Practice Periods I and II respectively, while subjects assigned to Groups 6 and 7 were scheduled to complete six iterations during Practice Periods I and II respectively.

The assignment of subjects to separate groups with four- and two-month retention intervals was done with the intention of using both retention interval and number of iterations as independent variables. As described below, scheduling problems precluded the use of retention interval as an independent variable in the data analyses.

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. FINAL CHECKRIDE	FC	· FC	2 MO.—→FC	FC	2 MO. — FC	FC	2 MO FC	
PRACTICE PERIOD II	6 МО.	—— 4 MO.	TWO 2 MO. FC	4 MO.	FOUR 2 MO. FC	4 MO.	SIX 2 MO. FC	
PRACTICE PERIOD I		TWO		FOUR TERATIONS		SIX ITERATIONS		
INITIAL	IC	1	1	IC	10	IC	10	
z	12	12	12	13	12	12	12	25
GROUP	1	2	3	4	5	9	2	

Figure 1. Subject Groups.

INSTRUCTOR PILOTS

Two Standardization Instructor Filots (SIPs) from DES and two SIPs from the Instrument Aviator Qualification Section (IAQS) served as SIPs for the initial and final checkrides. The DES SIPs were members of the standardization team responsible for evaluating U.S. Army aviator performance worldwide. The IAQS SIPs were members of a team responsible for giving annual checkrides to staff aviators at Fort Rucker. Staff IPs from USAAVNC agencies conducted the practice iteration flights. Task performance on the checkrides and practice flights was evaluated according to ATM standards using the rating scale described below.

AIRCRAFT

All checkrides and practice flights were given in the UH-1 aircraft.

ATM TASKS

The tasks chosen for evaluation in the study, along with the current FAC 2 semiannual iteration requirements, are listed in Table 2. A detailed description of these tasks can be found in Chapter 6 of TC 1-135, Aircraw Training Manual for the Utility Helicopter (Department of the Army, 1981). The task list was limited to 48 FAC 2 contact and terrain flight tasks in order to accomplish the checkride within a three-hour flight period.

Tasks were placed in a recommended order of completion on the data collection form to facilitate use of the form by IPs on checkride and practice flights. Because of numerous considerations, such as the airfield from which the flight would depart, the stagefields available on any particular day, air traffic, weather, and time constraints, the exact order in which the tasks actually were accomplished varied for some flights.

DEPENDENT VARIABLES

Checkride Task Scores

Task performance was rated in one of two ways, depending on whether the tasks were considered to be primarily psychomotor or procedural. The classification of tasks as psychomotor or procedural was based on the distinction made by Welford (1970). Tasks were considered to be psychomotor if the overt actions in olved in performing the task constituted the essential part of the task and, without which the purpose of the task would disappear. Tasks were considered to be procedural if the overt actions played a more incidental part of task performance, serving to give expression to the task rather than forming an essential part of the task.

Performance on the 33 psychomotor tasks (see Table 2) was rated by the IPs on the basis of a 12-point verbally anchored rating scale (reproduced in Figure 2). The content of the verbal descriptors was based on rating scales used by Holman (1978) and Bickley (1980) in

ATM TASKS EVALUATED

TASKS		FAC 2 SEMIANNUAL ITERATIONS
FLIGHT PLANNING TASKS		
1001 1003	**Plan a VFR Flight **Prepare DD Form 365F (Weight and Balance)	4
1004 1005	**Use Performance Charts **Prepare Performance Planning Card (PPC)	4
	Trepare retreament raming data (110)	•
BEFORE FLIGHT TASKS 1501	**Perform Preflight Inspection	3
1502	**Perform Before-Takeoff Checks	3
HOVERING TASKS 2001	Perform Takeoff to a Hover	2
2002	**Perform Hover (Power) Checks	3 3
2003 2004	Perform Hovering Turns Perform Hovering Flight	3 3
2005	Perform Landing From a Hover	3
TAKEOFF TASKS		
2501 2502	Perform Normal Takeoff Perform Simulated Maximum	3
2502	Performance Takeoft	3
BASIC FLIGHT TASKS		
3001	Perform Straight-and-Level Flight	4
3002 3003	Perform Climbs and Descents Perform Turns	4
3004	Perform Deceleration/Acceleration	4
3005 3006	Perform Traffic Pattern Flight **Perform Fuel Management Procedures	3 4
APPROACH AND LANDING TASKS	•	
3501	**Perform Before-Landing Checks	3
3502 3505	Perform Normal Approach Perform Steep Approach	3
3506	Perform Go-Around	2
3509 3510	Perform High Reconnaissance Perform Confined Area Operations	2 2
3511	Perform Slope Operations	2
3512	Perform Pinnacle/Ridgeline Operations	1
EMERGENCY TASKS	Destant Harrison Arbanatushina	,
4001 4002	Perform Hovering Autorotation Perform Low-Level Autorotation	1
4003 4004	*Perform Standard Autorotation With a 180-Degree Turn Perform Low-Level Autorotation	1
4005	Perform Simulated Hydraulic System Malfunction	2
4006 4007	Perform Simulated Antitorque Perform Manual Throttle Operation, Emergency Governor Mode	2 1
4008	Perform Simulated Engine Failure at Altitude	2
4009 401.9	Perform Simulated Engine Failure from Hover Altitude Perform Shallow Approach to a Running Landing	2 2
INSTRUMENT FLIGHT TASKS		
4506	**Perform Radio Communications Procedure	4
TACTICAL AND SPECIAL TASKS 5001	**Perform Terrain Flight Mission Planning	2
5002	**Perform Terrain Flight Navigation	2
5003 5005	Perform Low-Level Flight Perform NOE Flight	2 2
5007	Perform NOE Deceleration	2
5008 5009	**Perform Hover Out-of-Ground Effect (OGE) Check Perform Terrain Flight Takeoff	2 2
5010	Perform Terrain Flight Approach	2
AFTER LANDING TASKS		
6501	**Perform After-Landing Tasks	3
Note. Task numbers, categor *Deleted from task list.	ories, and names are those listed in TC 1-135, Utility H	lelicopter AT
**Procedural tasks.	10	
	13	

^{*}Deleted from task list. **Procedural tasks.

RATING	DESCRIPTION
1	Performance unsafe to the extent that the IP immediately had to take control of the aircraft.
2	Performance deteriorated until IP was finally required to take control of the aircraft.
3	Few of the ATM standards were met, student required considerable verbal assistance, but IP did not have to take control of the aircraft.
4	Less than half of the ATM standards were met, student required some verbal assistance and continually over/ under controlled.
5	Less than half of the ATM standards were met, required little verbal assistance, but frequently over/under controlled.
6	Majority of the ATM standards were met, student required little or no verbal assistance, but tended to occasionally over-control or accepted slight deviations while attempting corrections.
7	Majority of the ATM standards were met, little or no verbal assistance needed, performance generally smooth but occasionally over-controlled or was slow making necessary corrections.
8	All ATM standards were met, most deviations from desired state were quickly noticed and smoothly corrected.
9	All ATM standards were met, all deviations from desired state were immediately noticed and smoothly corrected.
10	All ATM standards were met. Majority of performance within IP standards.
11	All performance within IP standards, any deviations from desired state were small and immediately corrected.
12	Outstanding. No noticeable deviations from desired performance.

Figure 2. Task rating scale.

research evaluating simulator-to-aircraft transfer of training. The scale was modified on the basis of recommendations by IPs who regularly evaluate aviators' performance in continuation training. The verbal anchors included in the scale are statements describing pilot behavior along such dimensions as the amount of under- or over-controlling of the aircraft, the amount of verbal assistance required from the IP, and the percentage of ATM standards met.

In addition to the 1-12 numerical rating, IPs noted deviations from desired standards for the 33 psychomotor tasks by marking one of two categories for each standard. For example, a deviation from desired altitude was indicated as either LO or HI. These data were retained for later analysis.

Fourteen of the tasks were procedural (step-following) tasks (see Table 2). For these tasks, the IP marked the number of omissions or mistakes made by the subject. The numerical score on the procedural tasks was obtained by subtracting the number of omissions marked from an arbitrary maximum score of 9. Paper-and-pencil academic tests were developed by the DES SIPs to assess knowledge in the following procedural tasks:

- Plan a VFR Flight,
- · Prepare a Weight and Balance Form,
- Use Performance Charts,
- Prepare a Performance Planning Card (PPC), and
- Perform Fuel Management Procedures.

Academic tests were scored in the same manner as the other procedural tasks. Copies of the academic tests and reference material that were used by the aviators are included in Appendix B. A copy of the checkride data collection form is given in Appendix C.

Confidence Ratings

Confidence to perform each task to ATM standards was measured by using the same scale employed by Ruffner et al. (1981). Subjects placed a slash through a 100 mm line anchored at the left and right end-points with the verbal descriptors "Low Confidence" and "High Confidence," respectively. The resultant confidence score was calculated as the distance, in millimeters, from the left end-point to the subject's mark. The confidence rating form is shown in Appendix D.

PROCEDURE

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Initial Checkrides

The initial checkrides began during the second week of June 1982. Up to six test subjects were scheduled each day, three in the morning and three in the afternoon, depending on IP availability.

Subjects indicated their confidence to perform each of the tasks to ATM standards, both before and after the initial checkride. Subjects filled out the confidence rating form and completed the academic test portion of the initial checkride prior to beginning the inflight portion

of the checkride. On a few occasions, subjects completed part or all of the academic tests following the flight. From 2 to 2.5 hours were required to complete the checkrides.

During the weeks designated for the initial checkrides, several flights had to be rescheduled because of bad weather, maintenance problems, or unavailability of IPs. In some cases, a second flight for the initial checkride had to be scheduled to evaluate tasks not completed during the first flight that was shortened because of weather or maintenance problems. There was insufficient time to evaluate two of the test subjects on the eight terrain flight tasks.

Of the 81 initial checkrides, 56 were given by SIPs from DES and 16 were given by SIPs from IAQS. Because one of the IAQS SIPs was not available for one week of the initial checkrides, eight checkrides were given by IPs from ARI and Anacapa Sciences, and one checkride was given by an IP from the U.S. Army Aeromedical Center.

Practice Iterations

Practice iteration flights began during the third week in July, 1982 and ended during the second week in November, 1982. A practice iteration was operationally defined as one attempt by the subject to perform a task per flight. On a few occasions, a task not completed on a preceding flight was practiced more than one time on a subsequent flight. The following procedures were adopted to standardize the practice flights and to increase the likelihood that the test subjects would be able to practice entire tasks:

- Subjects completed special Weight and Balance exercises constructed by the DES SIPs prior to each flight. Copius of these exercises are given in Appendix E.
- IPs demonstrated the Antitorque Failure (Left and Right Pedal) tasks once prior to the subjects performing the tasks. The IPs also established the entry point for the Standard Autorotation task.
- Except for Antitorque Failures and Standard Autorotations, all tasks were performed by the subjects without IP demonstration or prior instruction.
- IPs gave the subjects constructive feedback after each task if the task was performed below the satisfactory level or if feedback was requested by the subject.
- Psychomotor and procedural tasks were evaluated by the staff IPs in the same manner as in the initial and final checkrides. The rating data for the practice flights were retained for later analyses.

An instruction sheet listing these procedures was attached to the front of the data collection form. The procedures were briefed to the staff IPs conducting the practice flights.

Final Checkrides

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The final checkrides began during the third week in November 1982. To keep the interval between the initial and final checkrides about the same, subjects were scheduled to take the final checkride in approximately the same order in which they had completed the initial checkride.

The final checkrides were conducted in the same manner as the initial checkrides. Both the subjects and the IPs were instructed prior to the flight not to discuss the number of iterations the subjects had been given during the practice periods or the subjects' flight hours to avoid contaminating the IPs' evaluation of checkride performance. The academic tests were completed by the subjects following the inflight portion of the checkride in order to minimize interference with airspace and stagefield usage.

As in the initial checkride, confidence ratings were completed both before and after the final checkrides. Following the completion of the post-checkride confidence rating, IPs debriefed the test subjects on their flight performance.

RESULTS

CHECKRIDE SCORES

Analysis of Variance

A one-way analysis of variance (ANOVA) was performed using the number of total flight hours as the dependent variable and the group to which subjects were assigned as the independent variable. The effect of group assignment was not significant (\mathbf{F} (6,74) = .14, \mathbf{p} < .05), indicating that subjects were randomly assigned to groups with respect to total flight hours.

Three of the 84 subjects discontinued participation in the study before they were able to take the initial checkride. Of the three subjects, one was transferred from Fort Rucker; one was withdrawn from the study by his superior due to conflicting duty requirements; and one was unavoidably sent on an extended temporary duty (TDY) assignment and was unable to return in time to take the initial checkride. A total of 81 subjects took the initial checkride.

Seventy-nine of the 81 subjects who took the initial checkride were able to complete the final checkride. One subject was removed from flying status midway through the study. Another subject was medically grounded and was unable to take the final checkride. Therefore, final checkride data were not available for these subjects. Seventy of the 79 final checkrides were given by the same IP who gave the subject's initial checkride. The nine checkrides not given by the same IP were nonsystematically distributed across the seven subject groups.

Means and standard deviations for the initial and final checkride raw scores are presented in Table 3. To permit the use of parametric statistical analyses, initial and final checkride raw data were transformed to normalized data following a method outlined by Hays (1967). Scores were normalized separately for each IP across initial and final checkrides. The normalization procedure is described in detail in Appendix F.

It became apparent during the first two weeks of practice flights that staff IPs would not be available as often as anticipated. This made it impossible to keep retention intervals of two- and four-months as originally planned. Therefore, inclusion of retention interval as a dichotomous independent variable was no longer practical. Instead, the data were analyzed using normalized final checkride scores as the dependent variable, with iteration groups and flight hour groups as independent variables.

For purposes of data analysis, subjects were placed in one of four iteration groups for each task. The first group consisted of the control group. The other three groups consisted of subjects who had completed two, four, or six iterations in a particular task, collapsing over practice periods. Subjects were also divided into two flight hour groups. The high flight hour group was composed of subjects with more than 900 total rotary wing hours; the low flight hour group was composed of subjects with less than 900 total rotary wing hours. Since the median number of flight hours was 915, this resulted in approximately the same number of subjects in both flight hour groups.

TABLE 3

MEANS AND STANDARD DEVIATIONS
FOR INITIAL AND FINAL CHECKRIDE RAW SCORES*

			TAL KRIDE	FINAL CHECKRIDE	
	ATM TASK	M	SD	Ä	SD
ι.	Plan VFR Flight	7.05	1,58	7.64	1.20
2.	Weight and Balance Form	4.47	1.87	6.17	2.04
3.	Use Performance Charts	7.47	1.59	8.14	1.20
٠.	Prepare Performance Planning Card (PPC)	7.20	1,60	8.06	1,04
<u>, </u>	Fuel Management	7.73	1, 39	7.96	1,16
<u>.</u>	Preflight Inspection	8,63	.78	8,41	. 5
7	Before Takeoff Checks	8,65	.66	8.08	1.17
3.	Communications Procedures	8.35	1.04	8.36	. 64
9,	After Landing Tasks	7,68	1,80	7.69	. 90
),	Takeoff to Hover	8,04	1,10	8.06	. 71
<u>. </u>	Hover Check	8.00	1.25	8.06	. 94
2,	Hover Turn	8.32	. 93	8,20	.49
3,	Hover Flight	8,54	. 94	8.23	. 4
٠,	Landing from Hover	8.03	. 93	8,08	. 7.
5,	Manual Throttle Operation	6.78	1.60	6.58	1.6
5.	Engire Failure at Hover	7.44	1.36	7,55	1.0
7	Hovering Autorotation	7.68	1, 22	7,65	9
<u>. </u>	Slope Operations	7,56	1.52	7.81	.7
) <u>. </u>	Traffic Pattern	7.71	1.21	8.09	.7
<u>). </u>	Climb/Descend	7.88	1.01	8.15	.5
<u>. </u>	Turns	7.87	104	8.17	.5
<u>. </u>	Straight-and-Level Flight	8.19	.87	8.06	.7
3.	Normal Takeoff	7,90	1.10	8.01	7
<u>+.</u>	Maximum Performance Takeoff	7.45	1.21	7.55	1.0
<u>5,</u>	Before Landing Checks	7.58	1.86	7.60	1,4
<u>5. </u>	Normal Approach	7.68	1,13	7.89	<u> </u>
<u> </u>	Steep Approach	7.47	1,15	7.63	8.
<u>3.</u>	Shallow Approach Running Landing	7.68	1, 25	7,92	.,9
<u>9.</u> _	Hydraulic Failure	7.18	1.54	6.89	1.8
) <u>. </u>	Antitorque Failure - Left	5.32	2.44	6,30	1.9
<u>. </u>	Antitorque Failure - Right Go Around	5,59	2.32	6.18	1.9
<u>?. </u>		8.00	1.14	8.17	.6
3. 4.	Standard Autorotation Low Level Autorotation	6.22	2.07	6.59	1.7
	Deceleration/Acceleration	6.50	1,53	6,82	1,6
5.	Engine Failure at Altitude	7.92 7.50	1.07	7,91	1.0
7. 3.	High Reconnaissance	7.74	1.69	7,83 8,23	.6
9.	Confined Area Operations	7.49	1.40	8,05	.8
".).	Pinnacle/Ridgeline Operations	7.51	1.84	7.76	1.1
1.	Terrain Flight Mission Planning	7.92	1.28	8.33	. 5
2.	Terrain Flight Navigation	7.48	1,99	8.05	1.2
3.	Low-Level Flight	8.12	1.09	8, 26	.7
2. 4.	NOE Flight	7.97	1.30	8,20	
" 5.	NOE Deceleration	7.25	1.54	7,59	1.2
<u>5.</u>	Terrain Flight Approach	7.71	1.45	8.26	. 7
7.	Out-of-Ground Effect Check	6.99	1.90	7.69	1.5
<u></u> .	Terrain Flight Takeoff	7.58	1.38	8.08	. 8

The initial checkride scores of one of the subjects in the control group were highly deviant from the rest of the group. Since including this subject's data would bias the statistical analysis, the subject's data were not used in the analysis of checkride scores. The data from five subjects who did not complete the scheduled number of iterations (i.e., 0, 2, 4, or 6) were not included in the analysis of variance. This resulted in a final sample size of 73 aviators for the analysis of variance. Missing values were estimated by the BMDP AM statistical program (Engelman, Frane, & Jennrich, 1977).

The task Perform Standard Autorotation with 180° Turn was removed as an ATM task during the research. Accordingly, it was deleted from the task list and not evaluated on the final checkride. This reduced the total number of tasks to 47.

Initial checkride normalized scores were used as dependent variables in a 2 (Flight Hour groups) x 4 (Iterations) x 47 (Tasks) ANOVA to determine if there were significant pre-treatment differences among the two Flight Hour Groups or among the four Iteration groups. Tasks were used as a within-subjects variable. The ANOVA was performed using the BMDP 2V repeated-measures program. No significant differences were found between Flight Hour groups (\underline{F} (1,65) = 2.29, \underline{p} <.05), among Iteration groups (\underline{F} (3,65) = 1.41, \underline{p} <.05), or for the Flight Hour x Iteration interaction (\underline{F} (3,65) = .54, \underline{p} <.05).

Normalized checkride scores for the 47 tasks were used as data in a 2 (Flight Hour group) x 4 (Iterations) x 47 (Tasks) x 2 (Initial Checkride Pretest-Final Checkride Posttest) ANOVA with repeated measures on the last two factors. The ANOVA was performed using the BMDP 2V statistical program. The results of the ANOVA are summarized in Table 4. Significant main effects were found for the independent variables of Flight Hours (p <.05) and Tasks (p <.01). Significant two-way interactions were found for Tasks x Flight Hours (p <.01), Tasks x Iterations (p <.05) and Pre-Post x Tasks (p <.01). None of the higher order interactions reached statistical significance (p <.05).

The amount of variance accounted for (ω^2) was also estimated for each main effect and interaction and is included in Table 4. Examination of the ω^2 values (Dwyer, 1974) indicates that a minimum of one percent of the total variance was accounted for by only two sources -- the main effects of Tasks and the interaction of Pre-Post x Tasks. A Tukey HSD test for pairwise comparisons (Kirk, 1968) indicated that mean final checkride scores were significantly greater than mean initial checkride scores for the following tasks: Plan VFR Flight, Prepare Weight and Balance Form, Use Performance Charts, Prepare Performance "lanning Card, Perform Terrain Flight Approach, and Perform Out-of-Ground Effect Check. final Mean checkride score significantly less than mean initial checkride score for the task Perform Before Takeoff Checks.

Raw score means for the four iteration groups for the initial and final checkrides are graphically presented in Appendix G. The graphs in Appendix G illustrate the average increase or decrease in mean proficiency score from the initial checkride to final checkride. The

Table 4

ANOVA Summary Table for Normalized Checkride Ratings

Source of Variance	<u>ss</u>	df	<u>ms</u>	<u>F</u>	ω 2
Between Subjects					
Flight Hours (FH)	42.44	1	42.44	5.26*	.006
Iterations (I)	14.73	3	4.91	.61	.000
FH x I	8.96	3	2.99	.37	.000
Error	524.82	65	8.07		.086
Within Subjects					
Pre-Post (P)	22.85	1	22.85	3.25	003ء
PxFH	0.00	1	0.00	0.00	.000
PxI	49.34	3	16,45	2.34	.005
PxFHxI	7.52	3	2.51	. 36	.000
Error	456.43	65	7,02		.075
Tasks (T)	1039.94	46	22,61	41.01**	.169
T x FH	37.35	46	.81	1.47*	.002
TxI	97.19	138	.70	1.28*	.004
T x FH x I	69.79	138	.51	.92	.000
Error	1648.25	2990	.55		.270
РхТ	82.47	46	1.79	4.13**	.010
PxTxFH	14.40	46	.31	.72	.000
PxTxI	67.21	138	.49	1.12	.001
PxTxFHxI	51.96	138	.38	.87	.000
Error	1299.46	2990	.43	•	.435

Note. *p <.05 **p <.01 satisfactory proficiency level of 8 (all ATM standards met) is noted by a dashed horizontal line. Raw score means and standard deviations for the four iteration groups are given in Table 5 for the total sample as well as for the two flight-hour groups. Means are rounded to the nearest whole number. Average proficiency was below 8 on both the initial and final checkrides for four tasks. Three of the four tasks are emergency tasks.

The correlation between overall initial checkride performance and overall final checkride performance for the 0 iteration group was calculated as an indication of the relationship between initial level of performance and level of performance following six months of no practice. A composite score (average of all 47 task scores) was used as an estimate of the overall level of performance for each subject, since the single overall rating was not obtained. Composite scores were calculated separately for both the initial checkride and the final checkride. The correlation between overall initial checkride performance and overall final checkride performance is .42 ($\frac{df}{dt} = 9$, $\frac{df}{dt} = 9$).

Correlations among total rotary wing flight hours, recent flight hours (within the last 12 and 6 months), and initial checkride normalized scores are presented in Table 6. The correlations of the flight hour variables and final checkride normalized scores are presented in Table 7. Retention interval (number of days between the completion of the last practice flight and the final checkride) was negatively correlated with five tasks and positively correlated with one task. No significant correlations were found between checkride performance and the variables of age, months since flight school graduation, and total simulator hours.

Factor Analysis

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Means, standard deviations, correlations of final checkride normalized scores with the final checkride composite scores, and intercorrelations for the final checkride normalized scores are given in Appendix H. Examination of the correlation matrix indicated that several groups of tasks had high intercorrelations. Therefore, a principal factors extraction with varimax rotation was performed on the final checkride normalized scores.

Six factors emerged that had eigenvalues greater than 1.0 and that had a minimum of four tasks with factor loadings of .45 (20% of shared variance) or greater (Comrey, 1973). These factors were initially rotated to an orthogonal solution. Factor loadings, communalities, eigenvalues, and percentages of common variance for the six factor solutions are given in Table 8. Tasks are grouped under the factor for which they show the highest significant loading and are listed in decreasing order of loadings for that factor. Table 8 indicates that tasks generally load high on one factor and low on the other factors. In only a few cases do tasks have sizable loadings on more than one factor.

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MEANS AND STANDARD DEVIATIONS FOR CHECKRIDE RAW SCORES: AVIATORS WITH MORE THAN 900 HOURS

O(N = 5)4 (N = 12)6 (N = 9)Initial Final Initial Final Initial Final Initial Final ATM TASK SD SD SD SD SD SD Plan VFR Flight 1.9 7 7 1.9 1.4 8 1.3 7 1.3 8 1.4 2. Weight and Balance Form 1.1 5 1.8 1.6 2.3 2.1 2.4 1.5 4 . 9 5 3. Use Performance Charts 1.6 7 2.5 1.6 9 2.0 1.6 1.8 8 9 8 4. Prepare PPC 1.6 8 . 8 1.6 1.8 1.6 1.7 8 . 9 8 5. Fuel Management 1.3 8 1.1 8 1.0 8 1.2 2.3 8 1.5 . 9 7 1.2 6. Preflight Inspection .0 5 9 . 8 8 1.2 . 5 . 4 8 . 5 7. Before Takeoff Checks .4 9 . 5 9 , 9 2.4 . 7 . 7 9 . 9 9 9 .4 8 Communications Procedures 8 1.1 8 . 5 1.2 . 7 В 9 . 5 . 4 . 5 9. After Landing Tasks 1.2 9 . 6 8 8 . 8 8 1.9 8 1.3 8 1.7 8 1.0 8 8 10. Takeoff to Hover 1.7 . 5 8 1.3 8 . 7 8 1,2 В . 8 9 9 8 . 5 Hover Check . 9 11. 9 . 5 8 1.3 7 1.4 8 1.3 8 . 5 8 1.5 8 . 5 Hover Turn 12. . 5 9 . 5 8 1.0 8 . 5 8 1.0 8 . 5 9 . 9 8 . 5 Hover Flight 13. 8 1.3 9 . 5 8 1.1 . 3 8 1.2 8 9 . 9 . 5 6 R 14. Landing from Hover R 1.3 9 . 5 8 1.0 8 4 R 1.0 8 . 5 8 4 R . 5 2.2 15. Manual Throttle Operation A 1.5 6 7 1.6 7 9 6 1.6 7 1.8 7 1.9 1.8 1,2 Engine Failure at Hover 1.6 16. 8 8 1.1 . 5 8 1.4 8 . 9 7 1.6 8 1.0 2.0 17. Hovering Autorotation 1.5 1.6 R 7 8 1.2 8 6 8 1.3 8 8 8 1.0 18 Slope Operations 1.4 8 . 6 8 1.5 8 , 8 1.1 8 <u>, 5</u> 8 1.9 8 . 3 8 8 19. Traffic Pattern 1.7 8 . 9 8 1.2 8 . 9 9 . 5 8 8 1..0 . 6 8 20. Climb/Descend 1.3 9 8 9 9 . 5 8 . 9 . 7 8 . 5 8 1.1 . 3 8 8 21. Turns 8 . 9 9 . 5 9 1.0 8 . 3 8 9 9 . 5 8 . 9 8 22. Straight and Level Flight 9 8 8 9 8 1.1 8 1.0 8 . 7 9 . 7 8 . 7 8 8 23. Normal Takeoff 1.7 9 8 . 9 8 1.1 . 6 8 8 Max. Performance Takeoff 24. . 9 8 1.2 1.6 1,3 8 В 1.1 . 5 25. Before Landing Checks 2.5 . 7 2.6 2.3 . 8 1.5 5 8 Normal Approach 26. . 9 A . 8 8 1.3 8 .5 8 1.2 8 . 8 1.0 8 . 4 27. Steep Approach 1.7 .8 7 1.1 8 . 8 7 1,2 8 7 1.0 8 1.1 Shallon App Running Land 28. 8 2.0 8 . 5 8 1.3 8 . 9 8 1.4 8 8. 7 1.1 8 9 29. Hydraulic Failure 8 1.6 8 . 5 7 1.8 7 1.5 8 9 8 8 6 1.9 7 1.7 30. Antitorque Failure - Left 3.4 6 3.0 6 2.4 7 1.8 2.1 7 1.5 6 1.7 6 1.1 6 31, Antitorque Failure - Right 2.3 6 3.1 2.5 7 1.7 2.0 2.0 2.0 8 6 6 6 7 6 7 32. Go Around 9 . 5 8 . 8 8 1.1 8 . 5 8 1.0 8 . 5 9 1.0 8 8 2.5 1.9 1.0 33. Standard Autorotation 7 8 8 8 2.1 8 1.3 2.1 6 1.2 6 6 6 34 Low Level Autorotation 7 1.5 7 2.9 7 1.3 7 1.8 6 1.8 7 1.6 8 1.2 7 1.2 36, Decel/Accel 1.4 8 1.1 8 1.3 8 . 9 1.2 8 1.0 8 .5 8 . 8 37. Engine Failure at Altitude . 9 , 9 1.6 8 8 8 1.9 8 . 6 7 В . 9 8 1.5 8 1.4 38, High Reconnaissance . 4 . 5 8 1.7 8 . 5 8 1.1 8 1.1 8 1.5 8 . 5 39, Confined Area Operations 9 , 5 8 . 5 1.9 8 . 9 8 1.4 8 . 3 8 1.6 8 1.0 40. Pinnacle/Ridgeline Operations . 5 . 8 8 2.3 8 7 1.3 8 1.1 7 2.0 .4 ٠7 8 Ter. Flight Mission Planning 41. 8 1.2 8 . 8 7 2.2 8 . 5 8 1.2 . 5 8 1.0 8 . 5 Ter, Flight Navigation 42. 7 2.7 2.0 2.6 . 9 8 1,2 8 . 7 1.0 8 7 7 8 8 . 4 43. Low-Level Flight 9 8 9 . 5 8 1.5 8 . 6 8 1.0 9 . 5 8 . 7 8 . 9 NOE Flight 1.5 44, 9 2.0 1.2 9 8 . 5 8 8 8 . 5 8 . 7 8 4 45. NOE Deceleration 1.4 . 8 1.4 1.0 R 8 1.5 8 2.0 3 1.4 8 8 8 8 1.1 Ter. Flight Approach 46. 8 1.2 . 8 1.1 8 . 5 8 . 7 8 . 7 5 8 8 1.4 8 47. OGE Check 2.2 8 1.6 7 2.0 8 . 9 7 1.9 .7 7 2.4 1.0 8 8 48. Ter. Flight Takeoff 1.3 . 9 3 1.4 8 7 1.9 8 8 . 7 8

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*Note. Task 35, Standard Autorotation with 180° Turn, was deleted from the task 11st.

INDER 5 (CONTINUED)

MEANS AND STANDARD DEVIATIONS FOR CHECKRIDE RAW SCORES:

AVIATORS WITH LESS THAN 900 HOURS 2 (N = 11) 6 (N = 8)0 (N = 6)4 (N = 11)Fina Initial Final Initial Final Inftial Final Inftfal AIM TASK SD SD SD SD SD Plan VFR Flight 7 1.6 8 . 5 7 1.0 . 9 1 2.2 8 1.1 9 . 7 2, Weight and Balance Form 4 4 1.4 1.9 2.2 1.8 7 2.2 4 1.3 .4 6 4 1.8 6 9 . 5 8 2.0 8 5 Use Performance Charts 8 1.9 1.6 8 . 9 9 3, . 5 7 8 8 7 1.9 8 7 1.2 8 9 4 4. Prepare PPC 8 1.2 8 1.8 1.4 8 8 1,3 8 1.0 1.2 8 1.0 7 1.5 8 . 7 5. Fuel Management 8 . 8 7 1,5 8 8 5 . 5 9 . 9 8 . 5 9 . 5 8 . 5 9 . 7 8 6. Preflight Inspection 9 4 8 . 5 9 Before Takeoff Checks 9 8 5 9 5 8 1.1 9 . 5 8 . 7 8 6 7. . 4 Communications Procedures 1.1 8. . 8 8 1.1 1,1 8 . 5 9 9 9. 2.5 9 After Landing Tasks 8 1.0 8 1.2 7 7 1.1 8 1.6 8 . 6 8 1.4 10. 1.1 1.4 1.0 . 7 8 1.0 5 Takeoff to Hover 9 8 8 6 8 8 8 8 11. Hover Check 9 8 8 1.4 8 1.1 8 1,1 8 1.2 8 . 6 8 1.9 8 . 5 12, Hover Turn 9 . 8 8 . 4 8 1.0 8 . 8 8 9 8 . 3 8 1.0 8 ٥, 13. 9 5 9 . 7 8 . 4 8 1.0 8 . 5 Hover Flight 8 4 8 8 8 8 1.7 3 9 8 Landing from Hover 1.8 4 . 8 8 8 6 8 8 4 14. 8 8 8 1.2 1,2 15. Manual Throttle Operation 1.7 6 1.9 7 1.6 7 1.1 6 1.8 6 6 1.8 1.7 7 1.7 7 . 8 1.6 16. Engine Failure at Hover 8 1.0 8 1.0 . 9 7 8 8 . 1.0 1.3 7. 1.0 17, Hovering Autorotation 8 1.0 . 9 8 6 8 8 В 8 18. Slope Operations 8 1.2 8 . 8 7 1.2 8 8 8 1.3 8 1.3 2,5 В . 5 19. Traffic Pattern 8 . 8 8 . 8 7 . 9 8 1.7 8 1.2 . 9 1.0 . 9 . 5 1.3 20. Climb/Descend 8 . 9 8 4 8 8 . 5 8 8 8 .4 1.3 1.3 21 Turns 8 8 8 6 8 9 8 6 8 8 8 8 4 22 Straight and Level Flight 9 . 5 8 1.0 8 1.1 8 6 8 5 8 6 8 . 9 8 . 7 23 Normal Takeoff 8 8 1.0 8 1,1 8 , В 8 . 8 8 .4 8 1,2 9 6 24 Max. Performance Takeoff 8 1.5 1.2 1.2 .9 7 1.0 7 1.4 1.1 8 5 8 25. Before Landing Checks 1.0 7 2.4 8 1.3 2.0 1.1 8 1.0 8 1.3 8 8 8 7 8 1.1 1.0 . 5 1.2 26. Normal Approach 8 8 .4 8 9 .8 27. Steep Approach . 8 . 5 1.3 1.1 1.0 8 .4 1.1 1.0 R 8 A 28. Shallow App Running Land 9 8 1.3 1.0 1.2 1.2 8 . 9 1.5 1.0 8 29. 2.4 Hydraulic Failure 8 . 5 7 1.5 8 . 8 7 2.3 7 1.6 5 2.3 6 . 7 2.5 2,0 2.4 30, Antitorque Failure - Left 6 2.2 6 6 2.9 6 2.3 2.0 4 6 1,4 31. Antitorque Failure - Right 2,5 5 2.1 2.7 2.2 2.3 2.0 2.7 2.0 6 5 6 6 6 32. 4 1.7 1.5 9 9 . 5 1.1 8 8 8 8 . 6 Go Around 5 8 8 8 7 1.9 1.1 2.2 2.2 1.6 2,7 1.8 33. Standard Autorotation 8 8 6 6 5 6 5 2.6 1.0 1,6 2,1 7 1.0 7 1,5 1.1 34, Low Level Autorotation 7 . 8 36. Decel/Accel 8 1.0 . 8 1.1 8 9 1.2 1.0 8 8 8 . 8 A R 1.3 37 Engino Failure at Altitude 8 1.9 8 . 7 2.0 7 2.3 . 7 7 1.3 8 6 A 38 High Reconnaissance 8 1.3 8 6 7 1.1 . 7 8 . 9 8 . 6 8 2.1 8 .4 8 39 Confined Ares Operations 1.5 1.0 . 8 1.5 8 , 9 8 1,0 8 1.4 8 . 9 8 7 40. 1.0 1.9 2.4 1.,9 8 3 9 . 6 1.2 Pinnacle/Ridgeline Operations 8 8 a 1.1 41, Ter. Flight Mission Planning 8 1.0 8 5 1.3 8 5 8 1,1 8 . 4 8 8 . 5 Ter. Flight Navigation 2.2 3.1 42, 1.1 2.0 1,2 8 2.0 . 5 8 43, Low-Level Flight 1.3 .8 8 1.1 . 9 8 1..0 Ü 1.2 1.1 8 . 5 8 8 1.6 1.0 . 8 44. NOE Flight 8 1.1 8 1.7 8 1.2 8 . 5 8 8 . 6 8 45. NOE Deceleration 7 1.2 8 .7 7 1.4 2.1 1.3 2.0 7 . 9 1.3 8 7 6 2.2 . 5 1.2 8 . 6 46. Ter. Flight Approach 1,1 8 1.7 1,5 9 . 5 8 8 8 8 47. OGE Check 2.3 2.3 8 1.5 1.8 1.1 7 2.6 1.3 1.1 48 Ter. Flight Takeoff 8 . 9 8 9 1.4 .6 1..8 1.3 1.1 8 1.5

*Note. Task 35, Standard Autorotation with 180° Turn, was deleted from the task list.

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TABLE 5 (CONTINUED)

MEANS AND STANDARD DEVIATIONS FOR CHECKRIDE RAW SCORES:

ALL AVIATORS 2 (N = 6 (N = 1.7)0 (N = 11) 7. (N = Initial Final nitial Fina. Initial Final Final Initial ATM TASK M M SD M SD М SD SD SD SD SD Plan VFR Flight 1.1 1. 1.9 8 1.0 8 8 1.2 8 1.5 8 1.1 1.8 2. 1.7 5 2.2 2.1 Weight and Balance Form 1.2 1.6 6 2.1 7 Use Performance Charts 8 1.3 8 2.1 7 1.6 8 . 7 7 1.6 8 1.3 7 1.8 A . 7 Prepare PPC 1.4 1.4 1.5 . 7 7 1.6 8 1.3 7 1.7 8 4. 8 8 8 Fuel Management 1.0 1.3 8 1.2 8 1.1 7 8 1.3 1.3 8 1,1 5, 8 7 1.8 8 6. Preflight Inspection 9 . 3 8 . 5 9 . 9 8 . 6 8 . 9 8 . 5 9 . 6 8 . 5 Before Takeoff Checks 9 8 . 5 8 . 7 9 7. . 4 9 . 7 8 1.9 9 . 7 6 8 7 . 5 8 Communications Procedures ٥ . 7 8 . 9 1.1 ٥ Q Q 8 8 8 8 . 6 8 9. After Landing Tasks 1.0 8 1.0 2.3 8 . 9 8 . 7 8 7 8 1.2 8 1.6 8 1.2 10, Takeoff to Hover 8 1.3 8 . 6 8 1.2 8 1.1 8 1.1 A . 7 8 1.0 8 6 Hover Check 9 8 8 11. . 8 1.1 8 1.2 8 1.3 1.2 6 8 1.7 8 5 8 Hover Turn 9 . 7 8 . 7 8 8 9 8 4 12. . 5 8 1.0 8 8 Q . 4 Hover_Flight 1.0 13. A 8 . 5 8 . 9 8 . 4 8 1.0 8 . 5 8 9 8 5 14. Landing from Hover 8 1.0 8 . 6 8 9 8 1.2 8 . 4 8 1.0 8 5 8 я 1.3 15, Manual Throttle Operation 1.9 6 1.7 7 1.7 7 7 1.4 6 1.8 6 1.6 6 8 16. Engine Failure at Hover 1.3 8 1.1 1.0 8 1.3 7 1.6 8 . 9 7 1.5 9 R A A 17. Hovering Autorotation 8 1.2 7 1.5 8 1.1 8 6 8 1,3 8 8 8 1.3 8 9 18. Slope Operations 8 1.3 8 . 7 7 8 8 8 1.2 8 1.0 7 2.3 8 4 1.3 19, Traffic Pattern 8 1.2 8 . 8 8 1.1 8 6 8 1.4 8 . 5 8 1.0 8 1.0 20. Climb/Descend 8 1.0 8 . 5 8 1.1 A . 4 8 9 8 . 6 8 1.1 8 . 6 Turns 21. 8 . 8 8 . 6 8 1.0 8 . 5 8 1.1 8 ٠,7 8 1.1 8 . 6 Straight and Level Flight 22. 9 . 6 8 1.0 8 1.1 8 . 8 8 . 7 8 ٠6 ь . 8 8 . 8 23. Normal Takeoff 1.0 7 . 9 1.2 8 8 1.1 8 Ŗ 1.0 8 6 8 1.1 8 24. Max. Performance Takeoff 8 1.2 7 1.2 7 1.4 8 1.1 7 1.1 7 1.3 7 1.2 8 . 5 Before Landing Checks 1.8 8 7 2.4 1.7 1.6 8 1.3 25. a 7 8 1.1 8 8 . 7 26. Normal Approach 8 1.1 8 . 7 8 . 8 8 .6 8 1.2 8 . 8 8 1.1 . 7 7 27. Steep Approach 8 1.2 8 . 7 7 1,2 8 1.0 8 1.1 8 1.1 8 1.1 28. Shallow App Running Landing 1.1 8 1.2 . 9 8 8 1.1 8 1.0 8 1.3 8 1.3 . 9 1.5 29. Hydraulic Failure 1.1 1.4 1.9 2.0 6 1.3 30. Antitorque Failure - Left 5 2.7 6 2.6 2,6 7 2.0 6 2.1 6 2.1 5 2,2 6 1,2 6 31, Antitorque Failure - Right 2.3 2.5 6 2.6 6 2.0 6 2.1 6 2.0 5 2.5 1.5 32. Go Around 9 1.5 8 .7 8 1,1 8 . 5 8 1.4 8 .7 8 1.1 8 8 33. Standard Autorotation 7 7 1.7 1.7 1.9 2.2 1.7 1.4 1.8 5 6 6 2.1 2.7 Low Level Autorotation 7 1.2 6 7 1.2 7 1.6 6 1,9 7 1.3 7 1.3 7 1.2 36. Dece1/Accel 1.0 9 8 1.0 8 1.0 Я 8 . 8 8 1.1 8 .9 8 . 9 8 37. Engine Failure at Altitude 1.5 8 1.0 8 1.6 8 . 7 7 1.8 7 1.2 7 1.9 1.2 8 38. lligh Reconnaissance 1.0 8 . 6 1.4 Я 6 8 1.0 8 . 9 8 1.7 В . 5 39. Confined Area Operations . 8 8 1.0 1.6 8 . 9 1.2 1.5 . 9 8 . 8 8 40. Pinnacle/Ridgeline Operations 8 8. 8 1.6 2.3 1.3 1.0 9 8 1.1 8 8 1.7 8 41. 1.8 Ter. Flight Mission Planning 8 1.0 8 8 8 . 5 8 1.1 . 5 8 1.0 8 . 5 42. Ter. Flight Navigation 2.0 7 1.9 7 2.0 8 1.6 8 8 . 5 8 2.1 8 . 5 1.6 43. Low-Level Flight 8 . 9 1,3 9 . 9 8 8 . 6 1,1 . 7 NOE Flight 44. 1.4 8 1.3 8 8 1.6 8 .6 8 1.4 8 8 . 8 8 . 6 . 6 45. NOE Deceleration 7 1.2 7 1.4 1.7 7 1,2 8 . 8 8 1.9 В 1.7 1,0 Ter, Flight Approach 46. 8 1.2 1.4 . 5 7 8 8 1.3 8 1.9 8 . 6 8 . 9 8 . 5 47. OGE Check 7 7 1.7 7 1.9 1.7 1.3 1.4 2.1 1.0 7 2.3 8 8 8 8 48. Ter. Flight Takeoff 8 1.1 8 1.2 7 1.7 8 . 9 8 1.2 8 .7 В 1.4 8 1.0

*Note. Twak 35, Standard Autorotation with 180° Turn, was deleted from the task list.

TABLE 6

CORRELATIONS BETWEEN INITIAL CHECKRIDE NORMALIZED SCORES AND ROTARY WING FLIGHT HOURS

AND ROTARY WIN	TOTAL	RW URS	RW HRS
	RW	LAST	LAST
ATM TASK	Hours	12 MOS.	6 MOS.
1. Plan VFR Flight	08	. 05	12
2. Weight and Balance Form	.00	. 07	.02
3. Use Performance Charts	13	07	-,09
4. Prepare Performance Planning Cards (PPC)	10	06	-,13
5. Fuel Management	-,07	.01	. 04
6. Preflight Inspection	.01	. 09	, 24*
7. Before Takeoff Checks	.03	.17	, 29*
8. Communications Procedures	.12	. 21	. 34*
9. After Landing Tasks	. 16	. 14	.15
10. Takeoff to Hover	.05	.03	. 21
11, Hover Check	.14	. 07	.03
12. Hover Turn	.07	.10	. 1.5
13, Hover Flight	. 07	. 1.7	. 27*
14. Landing from Hover	. 15	.09	. 1.8
15. Manual Throttle Operation	. 25*	.12	.17
16. Engine Failure at Hover	.37**	,00	.19
17. Hovering Autorotation	. 25*	.07	.23*
18. Slope Operations	. 24*	. 1,2	, 26*
19. Traffic Pattern	, 34**	. 16	, 15
20. Climb/Descend	. 24*	. 24*	.22
21. Turns	. 1.8	.12	.19
22. Straight-and-Level Flight	1.0	. 24*	, 30**
23. Normal Takeoff	.06	.18	. 254
24. Maximum Performance Takeoff	<u>. 26*</u>	. 15	.32**
25. Before Landing Checks	.10	. 14	.13
26. Normal Approach	, 20	.27*	, 35**
27. Steep Approach	.03	. 1.5	.23*
28. Shallow Approach Running Landing	.07	.12	. 24*
29. Hydraulic Failure	.13	. 25★	.19
30. Antitorque Failure - Left	.04	. 24*	.19
31. Antitorque Failure - Right	. 16	. 28*	. 22*
32. Go-Around	. 20	.07	.13
33. Standard Autorotation	. 21	.11	.02
34. Low-Level Autorotation	.11	.28★	. 21
36. Deceleration/Acceleration	02	.04	.17
37. Engine Failure at Altitude	.12	.04	.13
38. High Reconnaissance	.12	07	.03
39. Confined Area Operations	. 1.1	-,15	.01
40. Pinnacle/Ridgeline Operations	. 15	06	.06
41. Terrain Flight Mission Planning	15	.16	, 32**
42. Terrain Flight Navigation	12	, 21	. 23*
43. Low-Level Flight	.03	.13	.28*
44. NOE Flight	-,06	. 1.6	. 1.6
45. NOE Deceleration	. 25★	02	12
46. Terrain Flight Approach	, 20	. 04	.16
47. Out-of-Ground Effect Check	,02	, 30**	, 33**
48. Terrain Flight Takeoff	, 20	.07	.05

Note. *p <.05 **p <.01, N = 78

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TABLE 7

CORRELATIONS BETWEEN FINAL CHECKRIDE NORMALIZED SCORES
AND ROTARY WING FLIGHT HOURS

AND ROTARY WINC	TOTAL	RW HRS	RW HRS
	RW	LAST	LAST
ATM TASK	HOURS	12 MOS.	6 MOS.
1. Plan VFR Flight	03	.17	.08
2. Weight and Balance Form	02	.08	. 14
3. Use Performance Charts	 07	. 28*	. 21
4. Prepare Performance Planning Card (PPC)	02	.22*	.14
5. Fuel inagement	-,02	.06	.03
6. Preflight Inspection	. 11	.23*	. 25*
7. Before Takeoff Checks	,17	.10	, OR
8. Communications Procedures	.12	.13	. 20
9. After Landing Tasks	.12	.35**	. 24*
10. Takeoff to Hover	.18	.03	.16
11. Hover Check	.07	.08	.03
12. Hover Turn	.30**	.01	00
13. Hover Flight	.17	-,10	. 04
14. Landing from Hover	.33*	.11	.13
15. Manual Throttle Operation	.15	. 00	05
16. Engine Failure at Hover	.29**	, 04	.09
17. Hovering Autorotation	.21	.04	.03
18. Slope Operations	.16	.11	.14
19. Traffic Pattern	.18	. 08	, 04
20. Climb/Descend	.21	01	.05
21. Turns	. 25*	<u>,</u> 25*	. 1,7
22. Straight-and-Level Flight	.32**	. 25★	.19
23. Normal Takeoff	.18	.22*	. 34**
24. Maximum Performance Takeoff	.10	.33**	.31**
25. Before Landing Checks	.13	.17	.21
26. Normal Approach	.15	.05	.19
27. Steep Approach	.00	.18	.19
28. Shallow Approach Running Landing	.11	.27*	.19
29. Hydraulic Failure	.09	07	-,14
30. Antitorque Failure - Left	.22	,30**	. 30**
31. Antitorque Failure - Right	.23*	.21	. 29**
32. Go-Around	.06	.01	.07
33. Standard Autorotation	.11	<u>.40**</u>	, 29**
34. Low-Level Autorotation	.11	. 24*	, 32**
36. Decel/Accel	10	07	06
37. Engine Failure at Altitude	04	15	-,14
38. High Reconnaissance	.08	.10	-,01
39. Confined Area Operations	.14	.07	04
40. Pinnacle/Ridgeline Operations	.18	.18	.14
41. Terrain Flight Mission Planning	.04	.00	03
42. Terrain Flight Navigation	.08	.16	.13
43. Low-Level Flight	.13	.06	,05
44. NOE Flight	.17	.15	.06
45. NOE Deceleration	.03	09	19
46. Terrain Flight Approach	.16	, 20	.07
46. Terrain Flight Approach 47. Out-of-Ground Effect Check 48. Terrain Flight Takeoff	.16 .23*	19	11 03

Note. *p < .05 **p < .01, N * 78

TABLE 8

FACTOR LOADINGS, COMMUNALITIES, EIGENVALUES, AND PERCENTS OF VARIANCE FOR SIX FACTOR PRINCIPAL FACTORS EXTRACTION AND VARIMAX ROTATION OF ATM TASKS

ATM TASK	F ₁	F ₂	F ₃	F ₄	F ₅	F ₆	h ²
FACTOR 1	· · — · · · · · · · · · · · · · · · · ·						
Antitorque Failure-Left	, 71,	.13	.02	.10	. 36	. 17	.69
Standard Autorotation	.67	. 12	.11	.28	.07	.10	. 57
Antitorque Failure-Right	.66	. 1.3	.08	.21	. 27	.07	. 58
Hydraulics Failure	. 57	. 31	. 14	.08	.04	. 14	.47
Low Level Autorotation	. 56	.06	. 20	. 31	.16	.11	. 50
Engine Failure at Hover	. 55	. 14	.40	.15	.09	.10	.53
Hovering Autorotation	.52	. 19	. 29	. 20	.01	.14	. 44
Manual Throttle Shallow Approach to Running Landing	.46 .45	. 20 . 05	.15 05	.33 .23	00 .18	-, 05 -11	.39
ACTOR 2							
Low Level Flight	.06	.76	.02	.12	. 35	.11	.73
Terrain Flight Mission Planning	.15	.75	.18	.07	.18	.09	.66
Terrain Flight Takeoff	. 14	.72	.07	.20	.23	.15	.66
Out-of-Ground-Effect Check	08	.61	. 24	.16	.09	. 14	.50
NOE Flight	.31	.61	.05	,44	.08	.07	.67
Terrain Flight Navigation	. 28	.57	.07	.12	03	.01	. 28
Terrain Flight Approach	.10	. 52	.16	.48	.07	. 14	. 56
ACTOR 3	••		••				
Landing From a Hover	. 20	.05	.91	.06	.07	.11	. 90
Hovering Turn Hovering Flight	.12 .04	. 26	.83	.03	.06	.15	.79
Takeoff to a Hover	.12	. 28 . 07	.66 .65	.12 .07	.04 .22	.15 .10	.56 .51
Normal Approach	.42	.06	.54	.41	.01	.10	.65
ACTOR 4							
High Reconnaissance	.12	. 39	.07	.70	.04	. 09	.68
Confined Area Operations	.16	.16	.08	.60	.18	.10	.46
Pinnacle/Ridgeline Operations	. 39	. Õi	.05	.53	.13	.14	.48
Steep Approach	. 29	02	, 22	.52	.15	.16	.45
PACTOR 5							
Before Takeoff Checks	.01	. 21	.02	05	.73	.05	.58
After Landing Tasks	. 20	.09	.14	. 24	.60	.04	.48
Hover Check	11	04	.16	. 14	.57	04	. 38
Preflight Inspection	. 23	.46	.01	24	. 58	. 28	.73
Before Landing Checks	.17	. 25	.08	.08	. 50	.07	. 36
PACTOR 6							
Climb/Descend	, 22	. 20	. 28	. 36	13	•77	.78
Turns	. 31	. 26	. 24	.11	.16	.71	.77
Traffic Puttern Streight and Level Flight	,11	.17	. 21	. 34	.03	.68	.66
Streight and Level Flight	.21	.18	.22	.27	, 32	.67	.74
VARIABLES WITH FACTOR LOADINGS UNDER .45	22	7 7	22	18	03	Λ.E	05
Plan VFR Flight Weight and Balance Form	. 33	.11	. 23	-,15 - 10	21	.05	. 25
Performance Planning	. 28 . 3 4	.06 .08	.02 .10	10	15 20	.09	.12
Fuel Management	.23	.05	.02	.36 .12	13	26 13	.37
Radio Communication	.23	.31	.02	.07	.37	•05	. 29
Slope Operations	.44	.16	. 24	.02	.04	.26	. 34
Normal Takeoff	. 29	. 29	. 38	.22	.14	.18	.42
Maximum Performance Takeoff	.41	. 21	. 26	.30	.18	.15	.4:
Go-Around	. 15	.41	. 26	.06	.09	.09	. 28
Deceleration/Acceleration	.10	. 31	.05	.41	00	. 20	. 32
Engine Failure at Altitude NOE Deceleration	.21 .21	.43	. 16 . 38	.00	04 .07	.04	. 26
Sigenvalue							. 35
regenvalue Percent of Variance	13.00 56.30	2.79 12.10	2.41 10.40	1.93 8.30	1,51 6.50	1.49 6.40	
Cumulative Percent of Variance	56.30	6 8.40	78.70	87.10	93.60	100.00	

Note. N = 78

To check for the possibility of correlations among the factors, an oblique rotation was also performed. The oblique rotation yielded almost the identical ix factors, with no two factors correlating greater than .36. Therefore, orthogonal rotation was retained because of its conceptual simplicity and its ease of interpretation.

Examination of the tasks with significant loadings on each factor suggests the following descriptive labels: Factor 1 (56.3% of common variance) - Emergency Tasks; Factor 2 (12.1%) - Terrain Flight Tasks; Factor 3 (10.4%) - Hovering Tasks; Factor 4 (8.3%) - High-Angle Approaches; Factor 5 (6.5%) - Procedural Tasks; Factor 6 (6.4%) - Basic Flight Tasks.

Examination of the correlations between final checkride normalized scores and final checkride composite scores (Appendix H) suggested that overall checkride performance (as estimated by the composite score) could be reliably predicted by using a small set of predictor tasks that have high predictor-criterion correlations and low predictor intercorrelations (Landy & Trumbo, 1980). Two unique sets of ten tasks were formed by sampling tasks from the sir factors approximately in proportion to the number of tasks which had loadings greater than .45 on each factor. The sets are presented in Table 9. When tasks from the two sets are used as independent variables in separate multiple regression analyses to predict final checkride composite scores, a coefficient of multiple determination (R²) of .87 (corrected for shrinkage) is obtained (Stein, 1960).

CONFIDENCE RATINGS

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Means, standard deviations, and intercorrelations among the ratings on the 100-point confidence scale and the final checkride normalized scores for each of the 47 tasks are given in Appendix I. There are small or nonsignificant correlations between confidence ratings and checkride scores. In contrast, the confidence ratings obtained prior to a checkride are highly correlated with ratings obtained after the checkride.

TABLE 9

SETS OF ATM TASKS USED TO PREDICT FINAL CHECKRIDE COMPOSITE SCORE

TASK SET A

ANTITORQUE FAILURE - RIGHT
STANDARD AUTOROTATION
ENGINE FAILURE AT A HOVER
TERRAIN FLIGHT MISSION PLANNING
NOE FLIGHT
LANDING FROM A HOVER
CONFINED AREA OPERATIONS
STEEP APPROACH
AFTER LANDING CHECKS
STRAIGHT AND LEVEL FLIGHT

TASK SET B

ANTITORQUE FAILURE - LEFT LOW LEVEL AUTOROTATION HOVERING AUTOROTATION TERRAIN FLIGHT NAVIGATION TERRAIN FLIGHT TAKEOFF HOVERING TURN NORMAL APPROACH HIGH RECONNAISSANCE PREFLIGHT INSPECTION TRAFFIC PATTERN

DISCUSSION

The results indicate that the average level of flight performance in helicopter contact and terrain flight tasks is maintained after a six-month period of no practice. Furthermore, the average level of performance does not significantly increase with as many as six practice iterations. These finding applies to (a) both high flight time aviators (those with more than 900 totary wing hours) and low flight time aviators (those with less than 900 hours) and (b) both psychomotor tasks and procedural tasks. Overall final checkride performance can be predicted reliably using scores on a small number of tasks sampled from independent task dimensions. Self-rated confidence to perform final checkride tasks is not a reliable predictor of either initial or final checkride performance.

CHECKRIDE SCORES

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Analysis of Variance

The data from the analyses of the psychomotor tasks are consistent with past research on the retention of flight skills (e.g., Mengelkoch et al., 1960; Wright, 1973; Sitterley & Berge, 1972; Smith & Matheny, 1976) and the general literature on retention of psychomotor skills (e.g., Ammons et al., 1958; Parker & Fleishman, 1960). These studies indicate that skill levels for psychomotor tasks will be maintained at satisfactory levels for periods exceeding the six-month period used in the present study.

The lack of change in average proficiency level for the procedural tasks evaluated in this research (with the exception of an increase in average proficiency on the task Prepare Weight and Balance Form) was surprising. Based on past research, one would have expected some loss of proficiency on the procedural tasks after six months of no practice, even if no loss was observed on the psychomotor tasks. The results suggest that proficiency loss may be less severe for some types of procedural tasks than for others. This finding needs to be supported by additional research.

Most of the contact and terrain flight tasks examined in the present research have large psychomotor components. Many tasks that have large procedural components, such as the ATM FAC 2 instrument tasks and the ATM task Describe or Perform Emergency Procedures, were not evaluated in the present research because they are trained and evaluated in the UH-1 flight simulator. Past research indicates that losses in proficiency and improvements with practice may be found in procedural tasks such as these after a no-practice period of six months (Mengelkoch, et al., 1960). This warrants further examination.

Overall initial checkride performance was correlated $(\underline{r} = .42)$ with overall final checkride performance for the subjects that did not fly for six months. Although the correlation did not reach statistical significance—possibly due to the small sample size of the 0 iteration group $(\underline{n} = 11)$ —it is in the expected direction and is consistent with past research.

Performance did not improve on tasks for which the average performance was below ATM proficiency levels on the initial checkride. This finding was unexpected. Initial checkride performance that was below proficiency was primarily on emergency tasks (e.g., Antitorque Failures, Hydraulic Failure, Standard Autorotation, Low Level Autorotation).

Two factors may have contributed to the failure to demonstrate a significant improvement in the performance of these tasks. First, in order to control the number of times each task was practiced, flights were structured so that each task was practiced once without previous instruction or demonstration, with the exception of the two Antitorque Failure tasks that were demonstrated once by the IP before they were attempted by the subject. Tasks that are inherently difficult and for which initial skill is deficient or marginal may require extensive instruction, demonstration, and massed practice trials for significant performance improvement to occur in a six-month period. Second, more than six iterations of distributed practice may be required to either regain or retain proficiency in these tasks.

Factor Analysis

| 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000 | 10.000

The results of the factor analysis of final checkride normalized scores suggest the presence of independent dimensions underlying rotary wing contact and terrain flight skills. Although the sample size employed in the research (N = 78) is relatively small by standards adopted for factor analysis (Comrey, 1973), the six factors that emerged from the principal factors extraction and the varimax rotation appear to be reliable based on the size and pattern of factor loadings, eigenvalues, common variance accounted for, and communalities. The reliability of the factors should be investigated in additional research.

Examination of the tasks that loaded on each of the six factors suggests the descriptive categories of Emergency Tasks, Terrain Flight Tasks, Hovering Tasks, High-Angle Approaches, Procedural Tasks, and Basic Flight Tasks. The factors emerged on the basis of mathematical relationships among the variables; yet, with the exception of Factor 5, the groups are consistent with preexisting categories found in Army training literature defined on the basis of intuitive similarities of the tasks (e.g., Hovering, Terrain Flight).

It is noteworthy, in view of previous research in the area of flight skill retention, that a factor composed of procedural tasks was extracted independently from factors with tasks having large psychomotor components. Previous research indicates that psychomotor and procedural skills may have different proficiency maintenance requirements as well as different training requirements (Prophet, 1976).

The finding that overall checkride performance can be accurately predicted with a small subset of tasks has several implications for performance evaluation. These results suggest that it is possible to evaluate checkride performance with relatively few tasks, if the

individual tasks are highly correlated with overall checkride performance and are selected to sample relatively independent aspects of overall flight skill. The use of fewer tasks would reduce the time required for evaluation checkrides and save fuel and IP time, both being increasingly scarce resources in Army aviation.

CONFIDENCE RATINGS

As measured in the present study, self-rated confidence is not a reliable predictor of checkride performance. Similar data from the area of judgment and decision making (Lichtenstein & Fishhoff, 1977) indicate that subjects' predictions of task performance are subject to systematic biases, particularly overconfidence, and are generally not reliable predictors of actual performance. As stated previously, confidence ratings were obtained to provide data for exploratory analyses. The data, in conjunction with previous research, raise several questions about the viability of the construct of confidence.

GENERALIZABILITY OF RESULTS

The purpose of the present research is to validate, or determine the appropriateness of, the number of iterations required for Army aviators to maintain flight proficiency over a six-month training period. It is not possible to estimate from these data what flight proficiency loss might be expected for retention intervals longer than six months. The literature on the retention of flight skills suggests that significant decrements in flying proficiency might occur within a period of one to two years, particularly on flight tasks with large procedural components. Likewise, it is not possible to generalize directly from the data to emergency, instrument, night, or mission-specific tasks.

ARI is currently conducting research to evaluate the skill retention of Individual Ready Reserve aviators who have been trained to flight proficiency level and who have not flown for one year (Wick, 1983). Data from this research will provide an opportunity to examine the amount of proficiency loss among rotary wing aviators that occurs after a one-year retention interval. Additional research is needed to empirically investigate skill retention of rotary wing flight skills for periods longer than one year, using a representative sample that is large enough to allow examination of such variables as types of experience and types of flight tasks.

IMPLICATIONS FOR ATM PROGRAM

The results of the research have two major implications for the current ATM program. First, initial levels of aviator flight proficiency will be maintained in a large number of ATM FAC 2 contact and terrain flight tasks over a six-month period with little or no practice. No conclusion can be drawn about maintaining ATM standards in emergency tasks over six months. The data indicate that as many as six iterations of distributed practice without extensive instruction and demonstration may not improve performance in emergency tasks from an initial level of proficiency that is below ATM standards.

Second, the requirement for all aviators to fly current minimum semiannual FAC 2 iterations and for aviation field unit personnel to maintain records on performance of iterations for the majority of contact and terrain flight tasks may not be justified.

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CONCLUSIONS

The following conclusions are drawn from this research.

- 1. The average level of flight performance in helicopter FAC 2 contact and terrain flight tasks is maintained after a six-month period of no practice. Furthermore, the average level of performance does not significantly increase with as many as six practice iterations. Sufficient data are not available to generalize the findings to periods beyond six months or to instrument, emergency, night, or mission-specific tasks.
- 2. The results do not support the requirement for aviators to perform the current minimum number of ATM FAC 2 contact and terrain flight task iterations over a six-month training period.
- The total number of rotary wing flight hours is not a reliable predictor of an aviator's proficiency level at the end of a six-month period.
- 4. Overall final checkride performance can be reliably estimated using scores on a small number of final checkride tasks that are highly correlated with overall checkride performance and sampled from independent dimensions of flight skills.
- 5. Aviators' confidence ratings are not a reliable predictor of actual checkride performance.

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APPENDIX A DEMOGRAPHIC QUESTIONNAIRE

ATM QUESTIONNAIRE

1,	NAME: 2 DATE: (Day/Month/Year)
3,	NAME: 2 DATE: (Day/Month/Year) RANK: 4. SSN:
5.	AGE: Years 6, 551:
1.	DATE GRADUATED FROM FLIGHT SCHOOL: Month/Year
FOR BACI	- ITEMS 2 - 19. PLEASE CHECK [-] APPROPRIATE SPACES AND FILL IN THE BLANKS TO INDICATE YOUR TOTAL AVIATION KGROUND AND EXPERIENCE. MAKE YOUR BEST ESTIMATE OF HOURS ±50.
8.	PLEASE INDICATE YOUR ROTARY WING QUALIFICATIONS AND HOURS LOGGED BY AIRCRAFT TYPE.
	UH-1: { } Pilot { } UT { } IP { } SIP Total Hours AH-1: { } Filot { } UT { } IP { } SIP Total Hours OH-58: { } Prlot { } UT { } IP { } SIP Total Hours CH-47: { } Pilot { } UT { } IP { } SIP Total Hours UH-60: { } Pilot { } UI { } IP { } SIP Total Hours ROTARY WING IFE []
9,	PLEASE LIST OTHER ROTARY WING QUALIFICATIONS, IF APPROPRIATE:
	AircraftTotal Hours
	AircraftTotal Hours
	AircraftTotal Hours
	Total Rotary Wing Hours
10.	IF YOU HAVE SERVED A TOUR AS A ROTARY WING IP AT FORT RUCKER, INDICATE IN WHAT CAPACITY AND THE NUMBER OF HOURS YOU LOGGED:
	[] Contact Hours [] Tactics Hours
	[] Instruments Hours []-IP MOI Hours
	[] NH/NVG
11.	TOTAL ROTARY WING IP HOURS:
12.	PLEASE INDICATE YOUR ROTARY WING HOURS DURING THE:
	Previous 12 Months Previous 6 Months Previous 1 Month
13.	PLEASE INDICATE YOUR SIMULATOR HOURS: Total Hours Hours During Previous 12 Months
14.	PLEASE INDICATE YOUR FIXED WING QUALIFICATIONS AND HOURS LOGGED:
	[] Fixed Wing Military [] Fixed Wing Instructor [] Fixed Wing IFE
	Total Fixed Wing Hours Hours During Previous 12 Months
15.	DESCRIBE BELOW THE DUTY ASSIGNMENT/POSITION YOU HELD PRINK TO BEING ASSIGNED TO USAAVNC.
	11
16.	WAS PREVIOUS ASSIGNMENT IN AVIATION? [] YES [] NO
17.	WHAT FAC WAS YOUR PREVIOUS ASSIGNMENT? [] FAC 1 [] FAC 2
18.	DESCRIBE BELOW EACH DUTY ASSIGNMENT/POSITION YOU HAVE HELD AT FORT RUCKER DURING YOUR PRESENT TOUR.
	1.
	1.
9. 1	WHAT IS THE JOB TITLE OF YOUR PRESENT DUTY ASSIGNMENT?
't' \	WHAT WAS THE DATE OF YOUR PRESENT ASSIGNMENT TO FORT RUCKER?
	Honth/Year

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APPENDIX B ACADEMIC TEST MATERIALS

INSTRUCTIONS

- 1. This booklet contains reference material and data necessary to perform the following ATM tasks:
 - Plan VFR Flight
 - Prepare DD Form 365F (Weight and Balance)
 - Use Performance Charts
 - Prepare Planning Card (PPC)
 - Perform Fuel Management Procedures
- 2. This booklet will be used by a number of aviators during this phase of the ATM Validation Project. Please do not make any marks in the booklet or remove any pages from the booklet.
- 3. Answer sheets (DD Form 175, DD Form 365F, DA Form 4887-R) as well as a blank sheet for calculations will be provided.

100 WEST 340 BLURE CELLREE FORK F DD 365F ----VELTETA PROSECULAÇÃO Ĕ Transferred Lauren O Le Prompe Bank with and of electronistic del stafes 8448 To Cook GRABE POTTE OF PLANT 0 SCALLAG OF PROT IN COLUMNS MILITARY FLIGHT PLAN Cafe/*************

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Particular Services

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PUT. CHECK: FULLTIME

STARE.

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THE RESERVE THE PARTY OF THE PA	7101	44	- Troom	CALFACTOR		HEAVINGE THE	FG/% AVAR ICOMT	- 60-40-60 (10/10)	* PREDICT UNGUERFICIAL	MONTH OREGO, N.	TWO THOMPSON DAY	MAS RIC - ENDURANCE IAS	BEAT BANGE IAS	VALTSATION FACTOR	2A7E PEDAL MARGEN	(ABBreat			CAMBring Gwr			- TATE OF THE PARK	(TQ/%) AEG TO HOVER 10E	TO/N; REG TO MOVER OGE	SAN' PEDAL MARGIN	Da Farm 48*7-8 1 3-4 88
										Sacod on abecalt	performance for	atmesphasic	100.19002		•	Arrhad date is	Computed when	significe and	diferent from T/O	conditions			•	•	•	

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FIGURE 6-1 (Cant)

FIGURE 6-1

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FUEL CHECK DATA

	FUEL	TIKE	BASIC AIS
START:	1180	1400	OIL
			CREW OF
\$105:	1000	1423	TAXEOFF ;
			PASSENCE
			TESS FUE
FUEL CONSUMPTION RATE CHECK IS COMPLETED AT	ECK IS COMPL	ETED AT	
1425 HOURS WITH 980 LBS. OF FUEL REMAINING.	OF FUEL REM	AINING.	
			REMARKS:

WEIGHT & BALANCE DATA

	VEIGHT	HOMENT/100
BASIC AIRCRAFT	2600	1700
011	23	77
CREW OF (2)	200 EA	93 EA
TAXEOFF FUEL	1359	2078
PASSENCERS (2)	200 EA @	200 EA @ F.S. 117.0
LESS FUEL - (BASED ON LANDING WITH THE MOST CRITICAL FORWARD CG OF 73.2)	ASED ON LANDING WITH THE MOS CRITICAL FORWARD CG OF 73.2)	WITH THE MOST

- 1. FUEL USED IS JP-4
- CRASHWORTHY FUEL SYSTEM

VFR FLIGHT PLAN DATA

DEPARTURE DATA

UNIT	- USAAVHC	PRESSURE ALTITUDE		7000
AIRCRAFT NUMBER	- 68-16354	CALIBRATION FACTOR	•	58.0
TRANSPONDER WITH MODE "C" DEPARTURE TIME (Z) - DEPARTURE POINT - 1	1400 - OME AHP	FAT		+20
ROUTE OF FLICHT	- AO VANGARD	1/0 G4T		7500
FUEL ON BOARD	- 2 + 15	FLICHT CONDITION	8 .	VFR
WEIGHT & BALANCE	- 1 Jun 82			

WITH THE ABOVE INFORMATION, COMPLETE ALL ASTERISKED LIERS LISTED ON THE RW PERFORM-ANCE PLANNING CARD (PPC). ARRIVAL DATA ARE NOT SIGNIFICANTLY DIFFERENT FROM T/O CONDITIONS.

- ASSIGNED TO DES/FTR

CREW MEMBERS

C. D. JONES, DAC, 215 631554

BROWN, CW3, 154 605405

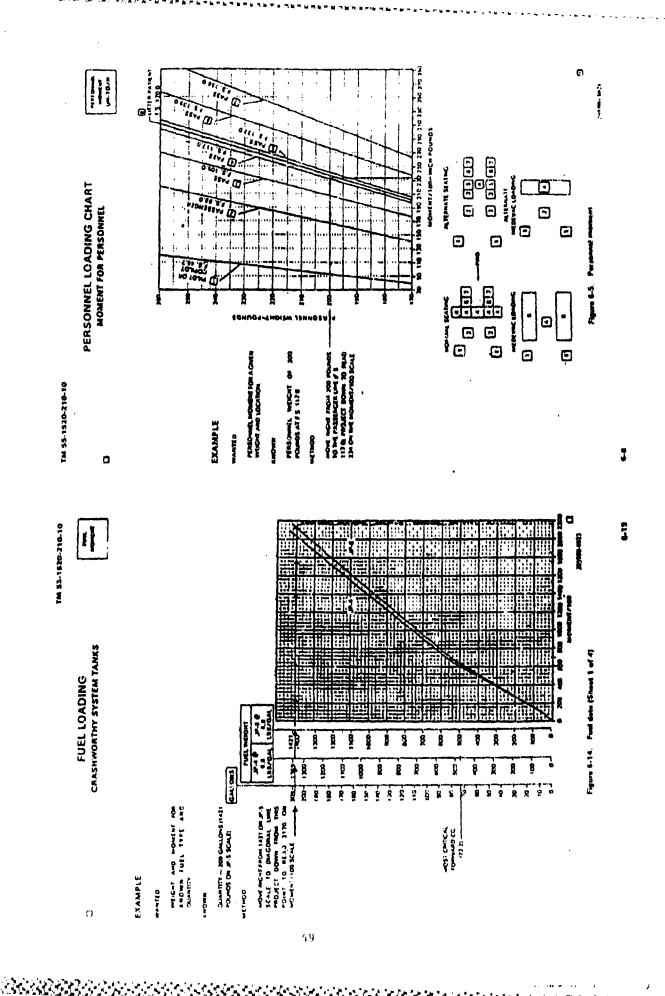
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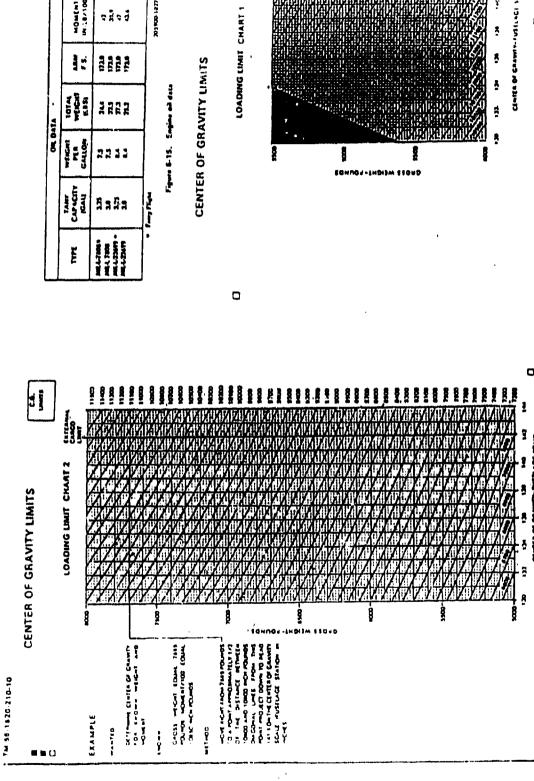
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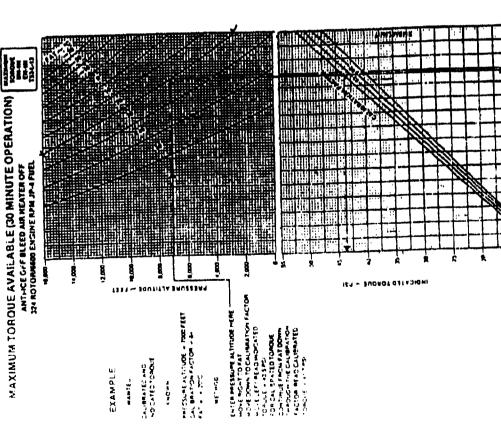
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	141.30			E				FEEDER CON	FINAL CON				308	592	251
	TOWER	CND CON	ATIS	NORTH CON	SOUTH CON	PIRATE CON	SAVAGE CON	(ANGEL) FEB	FIN	TOWER	REFUELING	COMMON FREQ	LOWE	BOLLWEEVIL	RUNKLE

VER FLIGHT PLAN DATA

ТОИЕ	TOWER 141.30 237.30 32.0	CND CON 265.60	ATIS 364.90	NORTH CON 365.20	SOUTH CON 233.10	FCC	PIRATE CON 394.00	SAVAGE CON 280.0	(ANGEL) FEEDER CON 373.50	FINAL CON 339.90	TOWER 240.80 46.	REFUELING 249.00	COMMON FREQ 50.	LOWE 308	BOLLWEEVIL 269	RUNKLE 251	
	UNIT - USAAVIC		75C71-67 GENUM LIFEGUIF		TRANSPONDER WITH MODE "C"	DEPARTURE TIME (Z) - 1400	DEPARTURE POINT - LOWE AHP		ROUTE OF FLICHT - AO VANGARD		FUEL ON BOARD - 2 + 15		FEICHT & BALANCE - 1 Jun 82		CREW HEMBERS - ASSIGNED TO DES/FTR	PILOI - C. D. JONES, DAC, 215 631554	COPILOT - M. B. BROWN, CW3, 154 605405







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LEVEL SURFACE CALK WIND HOVER 324 ROTORNSOO ENGINE RPM PHENSONE ALTITUCE — ESIN FT OAT — ZHY GNOSS WEICHT — BARBLB DESINED SAID NEIDHT — S FT TOWORLE PEDLIMED TO MOVER CHILL

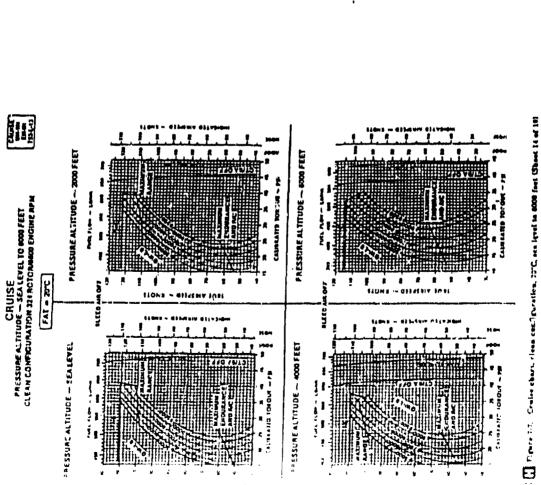
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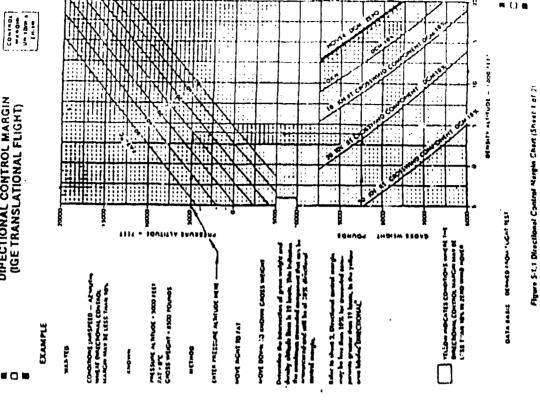
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CONGITUDINAL AND SIRECTIONAL CONTROL MARGIN (IGE TRANSLATIONAL FLIGHT)

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RED INCIDENTES ARRESTED LANGES

APPENDIX C

INFLIGHT DATA COLLECTION FORM

AND

TASK RATING SCALE

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ATH THELICHT DATA COLLECTION FORM

TH VALIDATION DATA COLLECTION FORM	INSTRUCTIONS FOR FINAL CHECKRIDE
TH VALIDATION	INSTRUCTIONS

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Aircraft are issued under 986-5 ADP code from Lowe Training Scheduling Branch (155-5835/5917). Log flight under aviator's exercy ADP Code with a -5 auffix, Mission code is AM3.

Please do not discuss with the aviator his group assignment or Aight hours.

Have aviator complete the PRE Confidence Rating Scale before the flight. Have him complete Academic Test and then the POST Confidence Rating Scale after the flight.

Give aviator feedback about his performance after the POST Confidence Rating Scale has been completed.

- Discuss which maneuvers need refresher training in order to meet AAPABF standards.
- indicate to aviator that, if he requests, he can have a DA Form 4507-1-R filled out for maneuvers that met AAPART standards during the checkride. Form 4507-1-R will be sent to him within two weeks of the dete of the final checkride. 'n
- Dr. Ruffner, ASI (198-6326); Dr. Bickley (255-2873).

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ALT CONTROL COORD

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ATH VALIDATION MANEUVER RATING SCALE

HATING	DESCRIPTION
-	Performance unsafe to the extent that the IP immediately had to take control of the dreaft,
~	Performance Ceterforated until 1P was Anality required to take control of the digraff.
-	few of the ATM etandards were met, student required considerable verbal assistance but IP did not have to take control of the direrall.
•	Less than half of the ATM standards were met, student required some verbal assistance and continually overfunder controlled.
•	Less than half of the ATM standards were met, required little verbal assistance but frequently overfunder controlled.
•	Mijority of the ATM standards were met, student required little or no verbal assistance, but tended to occasionally over-control or accepted slight deviations while attempting corrections.
	Majority of the ATM standards were met, little or no verbal assistance needed, performance generally smooth but occasionally over-controlled or was slow making necessary corrections.
•	All ATM standards were met, most deviations from desired state were quickly noticed and amouthly corrected.
•	All-ATM standards were met, all deviations from destred state were immediately noticed and amounty corrected.
2	All ATM standards were mot. Majority of performance within 1P standards.
	All performance within IP standards, any deviations from desired state were small and immediately corrected.
~	Outstanding. No noticeable deviations from desired performance.

APPENDIX O CONFIDENCE RATING SCALE

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APPENDIX E WEIGHT AND BALANCE PRACTICE EXERCISES

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APPENDIX F

DESCRIPTION OF PROCEDURE USED TO NORMALIZE RAW SCORE DATA

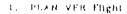
The, procedure used in this research to normalize the raw score data is based on a method for converting ordinal data to interval data. It is described in Hays' (1967) text Quantification in Psychology on pages 39-42. The procedure makes the assumption that the true values of aviator performance on the tasks are normally distributed.

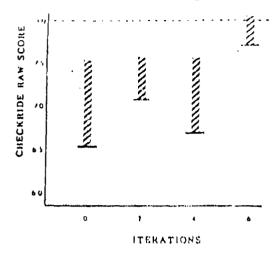
In this experiment IPs rated the checkride performance of subjects on each of the 47 tasks by using a 1 through 12 rating scale (see Figure 1). The observed performance on each task was placed in one of the twelve successive categories of the rating scale. The categories are successive in the sense that they form a logical progression from the lowest (1) to the highest (12) proficiency. The following steps are then followed for all initial and final checkride scores given by each IP.

- Determine the number of times the IP uses each of the 12 raw score categories across all tasks.
- Convert the total number of scores assigned to a category to a proportion of the total scores given by the IP.
- Determine the cumulative proportion of scores for each category.
- \bullet Find the point (\underline{z} score) on the normal distribution that corresponds to the cumulative proportion of scores at the lower and upper limit of each of the categories.
- Using a table of normal distribution densities and areas, find the mean z-score value for each of the categories using the formula:
- than of category = (density at lower limit)-(density at upper limit)
 (area below upper limit)-(area below lower limit)
 - The mean value for a category is the normalized score for that category. It is substituted for the corresponding raw score.

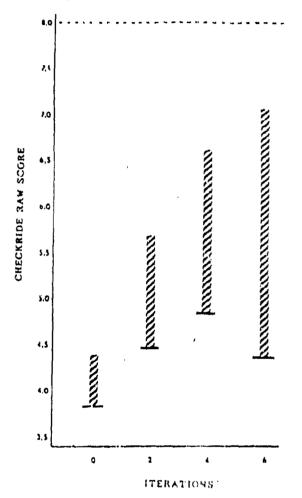
APPENDIX G

GRAPHICAL PRESENTATION OF INITIAL TO FINAL CHECKRIDE CHANGES FOR RAW SCORE ITERATION GROUP MEANS

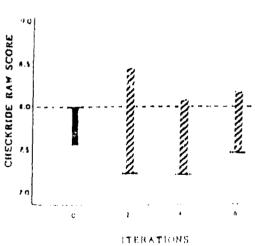




PREPARE WEIGHT AND BALANCE FORM

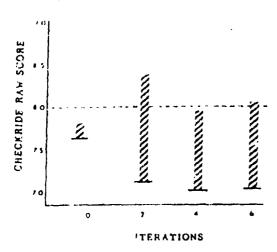


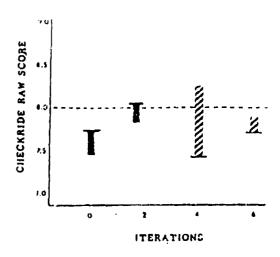


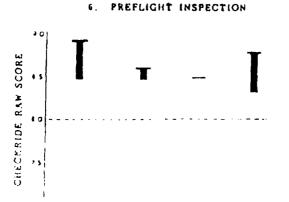


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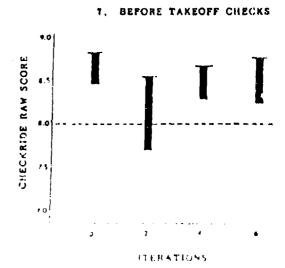
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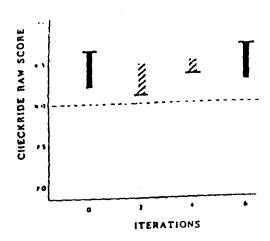


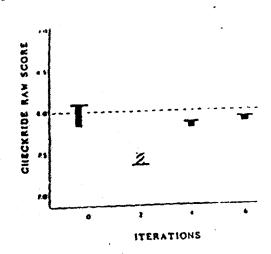


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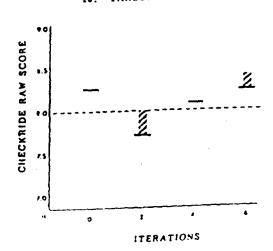


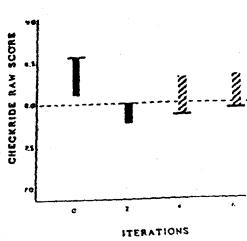




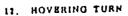
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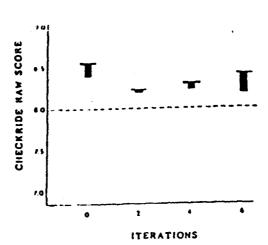
11. HOVER CHECKS



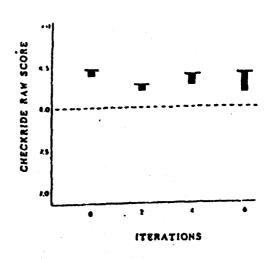


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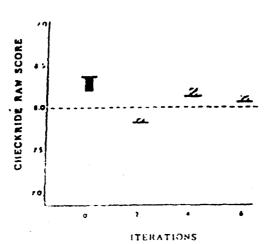




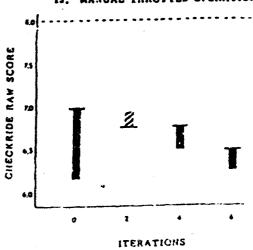
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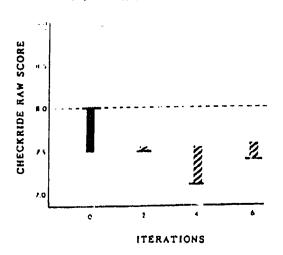
14. LANDING FROM A HOVER

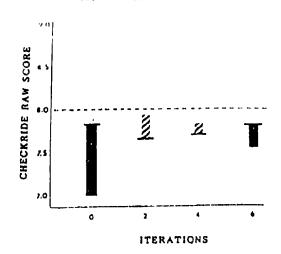


IS. MANUAL THROTTLE OPERATION

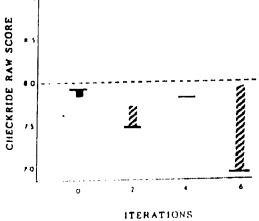


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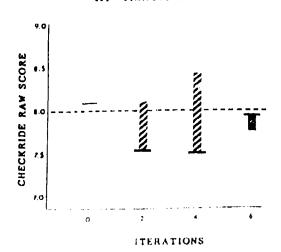




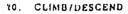
18. SLOPE OPERATIONS

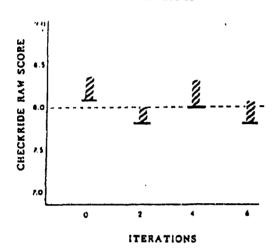


19. TRAFFIC PATTERN

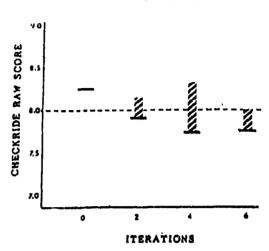


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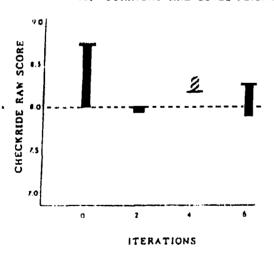




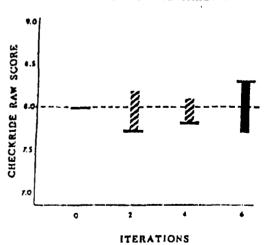
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22. STRAIGHT AND LEVEL FLIGHT

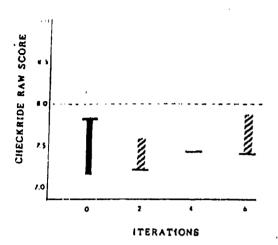


11. NORMAL TAKEOFF

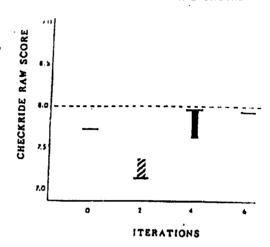


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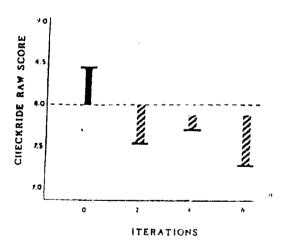




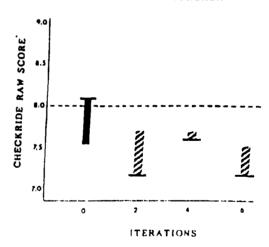
25. BEFORE LANDING CHECKS



26. NORMAL APPROACH

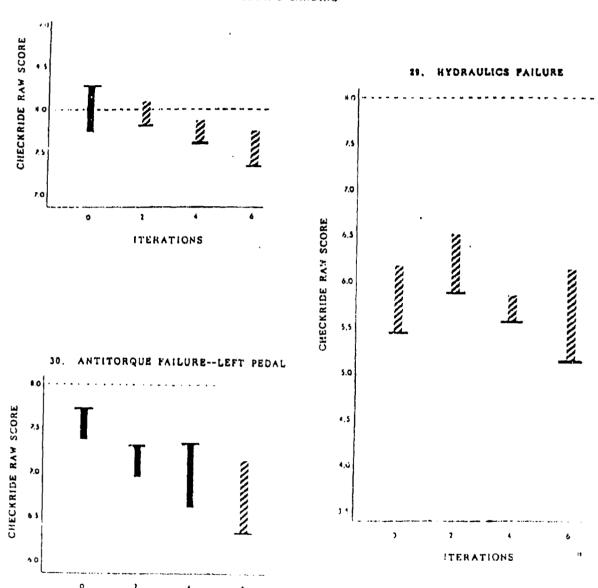


27. STEEP APPROACH



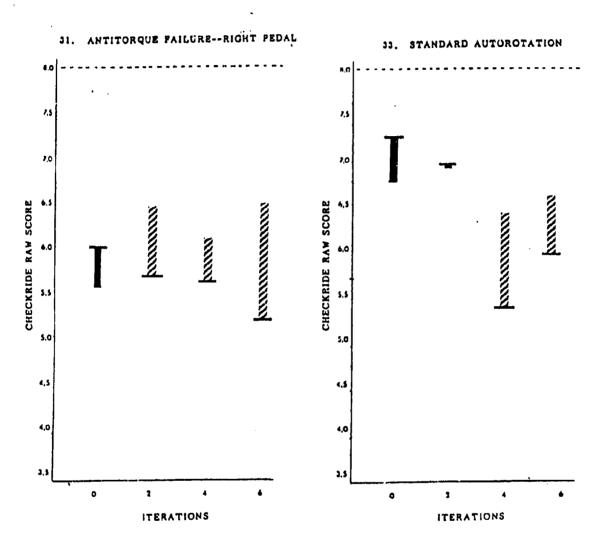
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28. SHALLOW APPROACH TO A RUNNING LANDING

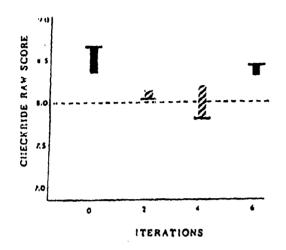


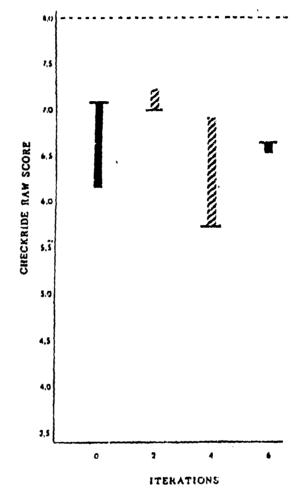
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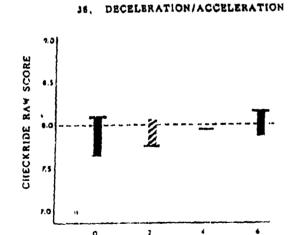
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Note. T - Decreese from Initial Checkride; 2 - Increese from Initial Checkride.







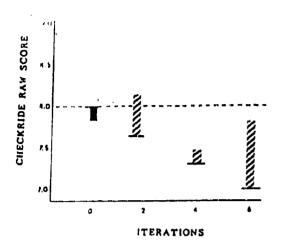
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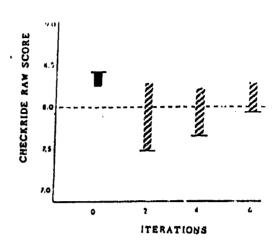
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17. ENGINE FAILURE AT ALTITUDE

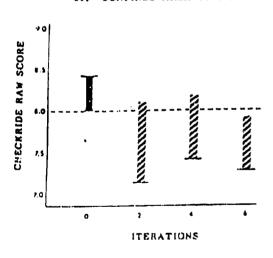
18. HIGH RECONNAISSANCE

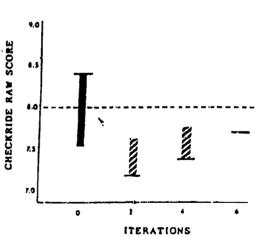




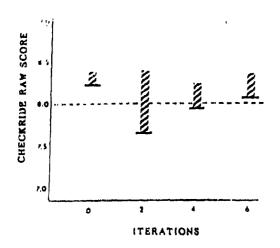
11. CONFINED AREA OPERATIONS

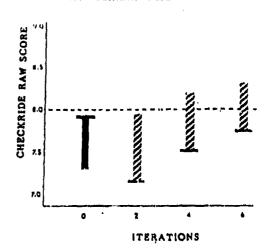
40. PINNACLE/RIDGELINE OPERATIONS

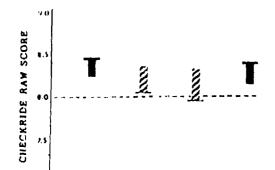




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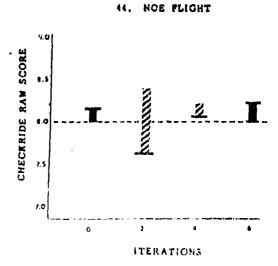




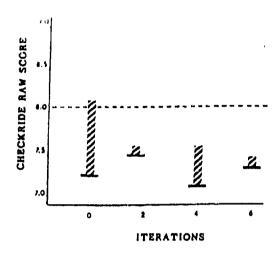


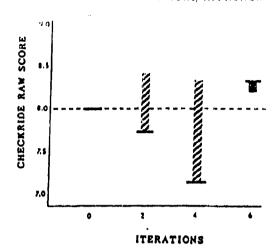
LOW-LEVEL FUIGHT

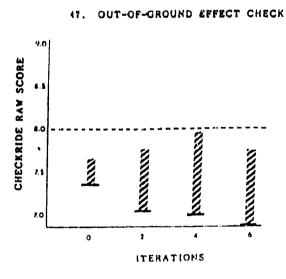
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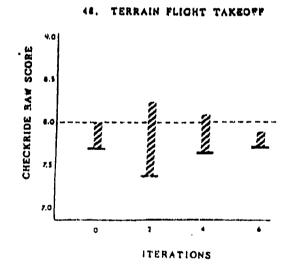


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Note. T . Decrease from Initial Checkride, Z . Increase from Initial Checkride

APPENDIX H

MEANS, STANDARD DEVIATIONS, TASK-COMPOSITE CORRELATIONS, AND CORRELATION MATRIX FOR FINAL CHECKRIDE NORMALIZED SCORES

. SCORE CORRELATIONS AMONG FINAL CHECKRIDE NORMALIZED SCORES

	, ATH TASK	Ħ	SD	<u>r</u> *
1.	Plan \FR Flight	.02	.95	.29
2.	Weight and Balance Form	67	1.38	.23
3.	Use Performance Charts	.47	.96	. 34
4.	Prepare Performance Planning Card (PPC)	.35	85	. 36
5.	Fuel Panagement	.30	1.02	.23
6.	Preflight Inspection	.57	.40	.46
7.	Refore Takeoff Checks	.32	.73	.28
8.	Communications Procedures	.51	.51	.45
9.	After Landing Tasks	06	.70	.48
10.	Takeoff to Hover	. 29	.57	.46
11.	Hover Check	.28	.62	.17
12.	Hover Turn	. 36	.43	.55
13.	Hover Plight	. 37	.42	.50
14.	Landin: from Hover	. 27	.53	.56
15.	Manual Throttle Operation	67	.87	.57
16.	Engine Failure at Hover	13	.81	.66
17.	Hovering Autorotation	05	74	.64
18.	Slope (perations	.01	.61	.52
19.	Traffic Pattern	. 25	.58	.53
20.	Climb/Lescend	.29	.44	.50
21.	Turns	.33	.55	.65
22.	Straight-and-Level Flight	.25	.62	.63
23.	Normal Takeoff	.21	.62	.64
24.	Maximum Performance Takeoff	11	.78	.68
25.	Before Landing Checks	06	.85	.45
26.	Normal Approach	.07	.65	.68
27.	Steep Approach	15	.66	.53
28.	Shallow Approach Running Landing	.16	.76	.45
29.	Rydraulic Failure	41	.96	.64
30.	Antitorque Failure - Left	78	1.02	• .66
31.	Antitorque Failure - Right	85	.97	.67
32.	Go-Around	.34	.47	.46
33.	Standard Autorotation	62	.98	.66
34.	Low-Level Autorotation	53	.93	.63
36.	Deceleration/Acceleration	.17	.73	.45
37.	Engine Failure at Altitude	.10	.76	.39
38.	High Reconnaissance	.43		.58
39.	Confined Area Operations	.23	.59	.51
40.		.04		.57
	Pinnacle/Ridgeline Operations Terrolo Flight Mission Planting		.72	
41.	Terrain Flight Mission Planning	.51	.40	.59
42.	Terrain Flight Navigation	. 37	.74	.52
43.	Low-Level Flight	.47	.51	.54
44.	NOE Flight	.41	.60	.68
45.	NOE Deceleration	04	.86	.52
46.	Terrain Flight Approach	.45	.50	.59
77.	Out-of-Ground-Effect Check	.10	.85	.46

a Correlations greater than .23 are significant at the .05 level. Those greater than .30 are significant at the .01 level. 82

	TASK	1	2	3	4	5	6	7	8	9	10	11	
1.	Plan VFR Flight		. 26	.02	.06	.15	.05	14	04	.03	.05	-,25	
2.	Weight and Balance	. 26		.07	.07	. 21	.07	14	.16	07	.10	14	
3.	Performance Charts	.02	.07		:36	. 18	06	19	.15	.13	. 20	lo	
4.	Prepare PPC	.06	.07	.86		.31	-,13	19	.07	.07	. 14	12	
5.	Fuel Hanagement	.15	.21	.18	. •31		08	-,02	01	.07	.01	00	
6.	Preflight Inspect	.05	.07	06	13	08		. 50	. 52	.38	.28	.16	
7.	Before T/O Checks	-,14	14	19	19	02	.50		, 33	.51	.10	.56	
8.	Radio Procedure	04	.18	.15	.07	01	.52	. 33		. 32	.27	.07	
9.	After Land Tasks	.03	07	. 13	.07	.07	.38	.51	.32		.25	32	
10.	T/O to Hover	.05	.10	.20	.14	.01	.28	.10	.27	.25		. 27	
11.	Hover Check	-,25	14	10	12	00	.16	.56	.07	.32	.27		
12.	Hovering Turn	.29	.04	.04	.03	.02	.20	.08	.17	.21	.59	.10	
13.	Hovering Flight	. 24	.06	.02	00	.03	.19	.10	.22	.11	.41	.04	
14.	Landing From Hover	. 29	.08	.18	.15	.09	.14	.14	.10	. 20	.70	. 24	
15.	Manual Throttle Opn	.16	.07	.26	. 29	.35	.04	.03	.20	. 30	. 15	.00	
16. 17.	Engine Fail Hover	. 26	.07 .21	. 24	.23	.04	.17	.07	26	.23	.32	.05	
18.	Hovering Auto Slope Operations	.19 .23	.12	. 34 . 02	. 36 . 05	.02 .06	.17	.05	.30	.05 .09	.31	.08	
19.	Traffic Pattern	.09	.11	01	01	03	.29 .14	.01 .15	.25 .19	.19	.17	.00 .10	
20,	Climb/Descend	.24	.13	04	02	.04	.29	.02	.07	.06	. 26	12	
21.	Turns	.15	.12	.14	.07	.01	.52	.13	.22	,29	. 36	.03	
22.	Straight/Level Flt	.05	.11	.04	04	02	.40	.13	.31	.40	.36	.19	
23.	Normal Takeoff	.12	.18	.30	. 30	.09	.36	.07	.28	,28	.43	.08	
24.	Max Performance T/O	.17	. 18	.31	. 28	.19	.25	.08	.24	.41	. 33	.09	
25.	Before Land Checks	03	.06	.02	06	.09	.41	.36	.31	,50	, 22	,39	
26.	Normal Approach	.24	.06	.41	. 38	.09	.04	.04	.24	,38	.41	~.05	
27.	Steep Approach	.01	08	.31	.27	.07	.13	.03	.15	,40	. 23	01	
28.	Shallow App Run Land	.05	.05	.03	.05	. 16	.23	.17	.13	. 20	.04	.13	
29.	Hydraulic Failure	. 23	.14	.06	.13	. 20	.27	.20	.13	,21	. 15	.08	
30.	Antitorque Fail-L	.15	. 15	.07	.08	.11	.45	.33	.29	. 39	. 26	.11	
31.	Antitorque Fail-R	.12	. 12	.27	. 29	.13	. 29	,28	.33	,31	.20	. 15	
32.	Go-Around	. 21	.00	.06	.15	.06	.24	.17	01	.19	.19	.03	
33.	Standard Auto	.29	.12	.32	. 39	. 13	.26	.07	. 28	. 25	. 22	01	
34.	Low Level Auto	.13	. 13	.21	. 22	.02	.21	.05	.32	. 28	.37	.08	
J6.	Deccl/Accel	.03	.07	.03	.06	. 12	.12	.03	. 25	.12	.01	.05	
37.	Eng Fail at Alt	. 23	. 05	01	04	-,10	.17	.07	.14	.01	. 07	07	
18.	High Reconnaissance	.06	04	.21	. 27	.14	.08	.05	. 16	, 22	. 21	. 14	
39 .	Confined Area Opns	.05	.03	.14	. 18	.05	.10	.19	.21	. 22	.:5	.31	
40.	Pin/Ridgeline Opns	.72	. 15	.13	. 23	.05	. 1 2	.08	.10	. 35	. 15	.06	
41.	Tur Flight Plan	.16	01	.07	.11	.04	.48	.30	. 36	.21	.21	.09	
42.	Ter Flight Nav	. 14	. 12	.31	. 26	.10	.31	.02	. 25	.11	.11	-,06	
43.	Low Level Flight	. 55	01	03	.06	.04	.53	.37	8٤.	. 34	. 20	. 15	
44.	NOE Flight	.06	.09	.19	. 32	.09	.33	.16	, 29	. 24	. 15	.01	
45.	NOE Deceleration	.09	02	. 06	. 05	01	. 26	.13	.17	.15	. 39	. 18	
40.	Ter Flight Approach	.11	.04	.18	. 25	.05	. 24	.07	.31	.22	. 24	.06	
	OGE Check	02	.03	00	.04	.03	.30	.25	. 36	.19	. 2 .	76	
47.	Ter Flight Takeoff				.10	.08	. 57	. 26	. 32	. 28	. 22	Q٤	

TASK VFR Flight t and Balance rmance Charte re PPC Management ight Inspect e T/O Checks Procedure Land Tasks o Hover Check ing Turn ing Flight	.24 .06 .02 00 .03 .19 .10 .22 .11	.29 .08 .18 .15 .09 .14 .14	15 .16 .07 .26 .29 .33 .04 .03	.26 .07 .24 .23 .04 .17	.17 .19 .21 .34 .36 .02 .17	.23 .11 .02 .05 .06 .29	.09 .11 01 01 03 .14	20 .24 .13 04 02 .04 .29	.15 .12 .14 .07 .01	.05 .11 .04 04 02 .40	.12 .18 .30 .30 .09	.1 .3212
t and Balance rmance Charts re PPC Management ight Inspect a T/O Checks Procedure Land Tasks o Hover Check ing Turn ing Flight	.06 .02 00 .03 .19 .10 .22	.08 .18 .15 .09 .14 .14 .10	.07 .26 .29 .33 .04 .03	.07 .24 .23 .04 .17	.21 .34 .36 .02	.11 .02 .05 .06	.11 01 01 03	.13 04 02 .04	.12 .14 .07 .01	.11 .04 04 02	.18 .30 .30 .09	.1
t and Balance rmance Charts re PPC Management ight Inspect a T/O Checks Procedure Land Tasks o Hover Check ing Turn ing Flight	.06 .02 00 .03 .19 .10 .22	.08 .18 .15 .09 .14 .14 .10	.07 .26 .29 .33 .04 .03	.07 .24 .23 .04 .17	.21 .34 .36 .02	.11 .02 .05 .06	01 01 03	04 02 .04 .29	.14 .07 .01	.04 04 02	.18 .30 .30 .09	. 1 . 3 2
rmance Charts re PPC Management ight Inspect e T/O Checks Procedure Land Tasks o Hover Check ing Turn ing Flight	.02 00 .03 .19 .10 .22 .11	.18 .15 .09 .14 .14 .10	.26 .29 .35 .04 .03	.24 .23 .04 .17	.34 .36 .02	.02 .05 .06 .29	01 01 03	04 02 .04 .29	.14 .07 .01	.04 04 02	.30 .30 .09	.3
re PPC Management ight Inspect e T/O Checks Procedure Land Tasks o Hover Check ing Turn ing Flight	00 .03 .19 .10 .22 .11	.15 .09 .14 .14 .10	.29 .33 .04 .03	.04 .17 .07	.02	.05 .06 .29	03 .14	.04 .29	.07 .01 .52	04 02 .40	.30 .09 .36	:
Menagement ight Inspect e T/O Checks Procedure Land Tasks o Hover Check ing Turn ing Flight	.03 .19 .10 .22 .11	.09 .14 .14 .10	.33 .04 .03 .20	.04 .17 .07	.02	.06 .29	03 .14	.04 .29	.01 .52	02 .40	.09 .36	
ight Inspect e T/O Checks Procedure Land Tasks o Hover Check ing Turn ing Flight	.19 .10 .22 .11	.14 .14 .10	.04 .03 .20	.17	.17	. 29	.14	.29	.52	. 40	.36	
e T/O Checks Procedure Land Tasks o Hover Check ing Turn ing Flight	.10 .22 .11	.14 .10 .20	.03 .20	.07								•
Procedure Lend Tasks o Hover Check ing Turn ing Flight	.22 .11 .41	.10 .20	. 20						. 13	. 27	,07	. (
Land Tasks o Hover Check ing Turn ing Flight	.11	.20			.30	. 25	.19	.07	. 22	.31	.28	•
o Hover Check ing Turn ing Flight	.41		.30	.23	.06	.09	.19	.06	. 29	.40	. 28	
Check ing Turn ing Plight		.70	.15	.32	.31	. 19	, 20	. 26	.38	. 36	.43	•
ing Turn ing Flight		,24	,00	.05	,08	.00	.10	12	.03	. 19	.08	
ing Flight	. 69	.80	.25	.43	.34	. 32	.31	.41	,42	. 38	.42	
		.65	. 26	.34	,25	. 30	.33	.34	,32	. 33	,53	
	. 65		.23	.48	.38	. 32	.32	.39	.40	.37	.45	•
l Throttle Opn	.26	.23		.38	. 36	,31	.22	.12	.19	. 32	. 35	
e Fail Hover	. 34	.48	.39		.70	.43	.30	.35	.37	. 38	.33	
				.70			. 35	.35	.40	. 39	.34	•
ing Auto	.25	,38	.36		41	.41		-				
												•
/Descend												٠
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ound												
/Accel	.33	.06	.32	.18	.16	.34	.40	.31	. 20	. 27	.23	
	. 32	.21	.29	.31	. 27	. 21	.16	.15	.19	.15	. 23	
	. 24	.19	.30	. 30	. 32	.14	. 39	. 25	.33	.31	.30	
•	. 24	. 23	. 36	. 25	. 33	. 24	. 30	.15	.23	.40	. 29	
	.19	.23	.45	. 28	.31	.20	. 30	. 24	. 29	.37	.32	
light Plan	. 30	.23	.24	.32	. 29	. 32	. 23	. 32	42	. 30	. 42	
light Nav	.14	.18	. 29	. 25	. 35	. 25	. 16	. 2 2	. 29	. 25	. 32	
evel Flight	.22	.13	.23	. 21	. 2 1	. 14	. 34	, 22	. 36	.40	. 35	
light	.22	.18	. 35	.33	. 39	. 37	. 32	. 24	. 38	. 34	. 40	
	.35	.41	.13	.41	. 33	. 41	.28	. 37	.40	. 26	, 22	
light Approach	.32	. 24	. 20	. 29	.34	. 11	. 40	.32	.39	. 39	. 29	
neck	.42	. 25	.17	.17	. 17	.10	36	. 27	. 27	. 29	. 17	
light Takeoff	.37	.15	. 28	. 27	. 27	.16	. 27	. 24	.44	.44	.46	
	Operations ic Pattern /Descend ght/Level Flt 1 Takeoff erformance T/O e Land Checks 1 Approach Ow App Run Land ulic Failure orque Feil-L orque Fail-R ound ard Auto evel Auto /Accel sil at Alt Reconnaissance ned Area Opns light Plan light Nav avel Flight light cceleration light Approach heck light Takeoff	Operations .30 ic Pattern .33 /Descend .34 .32 ght/Level Flt .33 l Takeorf .52 erformance T/O .31 e Land Checks .15 l Approach .51 Approach .23 ow App Run Land .18 ulic Failure .24 orque Fail-L .11 orque Fail-R .21 ound .35 ard Auto .11 evel Auto .18 /Accel .33 sil at Alt .32 Reconnaissance .24 indgeline Opns .19 light Plan .30 light Nav .14 avel Flight .22 light .22 cceleration .35 light Approach .32 heck .42 light Takeoff .37	Operations .30 .32 ic Pattern .33 .32 /Descend .34 .39 .32 .40 ght/Level Flt .33 .37 l Takeoff .53 .45 erformance T/O .31 .38 e Land Checks .15 .17 l Approach .51 .54 Approach .23 .30 ow App Run Land .18 .13 ulic Failure .24 .27 orque Feil-L .11 .24 orque Feil-L .11 .24 orque Fail-R .2: .27 ound .35 .31 ard Auto .11 .29 evel Auto .18 .30 /Accel .33 .06 sil at Alt .32 .21 Reconnaissance .24 .19 ned Area Opns .24 .23 idgeline Opns .19 .23 light Plan .30 .23 light .22 .18 eccleration .35 .41 light Approach .32 .24 heack .42 .25 light Takeoff .37 .15	Operations	Operations	Operations	Operations	Operations	Operations .30 .32 .31 .43 .41 .27 .41 ic Pattern .33 .32 .22 .40 .35 .27 .62 /Descend .34 .39 .12 .35 .35 .41 .62 .32 .40 .19 .37 .40 .39 .60 .78 ght/Level Fit .33 .37 .32 .38 .39 .33 .74 .56 1 Takeoff .53 .45 .35 .33 .34 .39 .36 .33 etand Checke .15 .17 .23 .25 .16 .19 .19 .04 1 Approach .51 .54 .41 .55 .46 .38 .40 .40 Approach .23 .30 .27 .33 .27 .19 .33 .28 ov App Run Land .18 .13 .33 .18 .2	Operations .30 .32 .31 .43 .41 .27 .41 .39 ic Pattern .33 .32 .22 .40 .35 .27 .62 .60 /Descend .34 .19 .12 .35 .35 .41 .62 .78 ght/Level Flt .33 .37 .32 .38 .39 .33 .74 .56 .74 1 Takeoff .53 .45 .35 .33 .34 .39 .36 .33 .49 etformance T/O .31 .38 .38 .42 .39 .32 .28 .37 .52 e Land Checke .15 .17 .33 .25 .16 .19 .19 .04 .25 1 Approach .51 .54 .41 .55 .46 .38 .40 .40 .37 Approach .23 .30 .27 .33 .27	Operations	Operations

	TASK	25	26	27	28	29	30	31	32	33	34	36	37
1.	Plan VFR Flight	03	. 24	.01	.05	.23	.15	.12	, 21	.29	.13	.03	. 23
٤.	Weight and Balance	.06	.06	08	.05	.14	.15	.12	.00	. 1 2	.13	.07	.05
١.	Periormance Charts	.02	.41	. 31	.03	.06	.07	.27	.06	.12	.21	.03	01
4.	Prepare PPC	06	. 18	. 27	.05	.13	.08	.29	. 15	. 39	.22	.06	04
5.	Fuel Hanegement	.09	.09	.07	.16	.20	.11	.13	.06	.13	.02	, 12	10
6.	Preflight Inspect	.41	.04	.13	. 23	.27	.45	. 29	.24	. 26	.21	.12	.17
7.	Before T/O Checks	.36	.04	.03	.17	.20	.33	.28	.17	.07	.05	. 33	.07
8.	Radio Procedure	.31	.24	. 15	.13	.13	.29	.33	.01	, 28	.32	.25	. 14
9,	After Land Tasks	.50	.38	.40	. 20	.21	.40	.31	.19	. 25	.28	.12	,01
'n,	T/O to Hover	.22	.41	.23	.04	.15	.26	. 20	.19	. 22	.32	.01	.07
11.	Hover Check	. 39	05	01	.13	.08	.11	.15	.03	01	.08	. 05	07
12,	Hovering Turn	.15	.50	. 26	.04	.32	.23	.16	.41	. 28	.34	.15	, 23
13.	Hovering Flight	.15	.51	.23	.18	.24	.11	.21	.35	.11	.18	. 33	. 32
14.	Landing From Hover	.17	.54	.30	.13	.27	.24	.27	.31	.29	.30	.06	.21
15.	Manual Throttle Opn	.33	.41	.27	.33	.45	.33	.37	.19	. 29	.33	.32	. 29
16.	Engine Fail Hover	. 25	.55	.33	.18	.38	.45	.53	35	.53	.50	.18	.31
17.	Hovering Auto	.16	.46	.27	.26	.43	. 36	.47	.27	.44	. 39	.16	. 27
18.	Slope Operations	.19	.38	.19	.18	.35	.38	.36	. 19	. 34	.35	.34	. 21
19.	Traffic Pattern	.19	.40	.33	. 12	. 24	.24	.33	.26	. 29	. 38	.40	. 16
20.	Climb/Descend	.04	.40	. 28	.16	.40	.25	, 21	. 33	. 25	.21	.31	. 15
21.	Turns	. 25	.37	. 37	.31	.42	.41	, 32	. 29	. 36	.34	,20	. 19
22.	Straight/Level Flt	.46	.35	. 35	.26	.25	.40	.36	. 25	. 38	.36	, 27	. 15
23.	Normal Takeoff	.21	.52	. 32	.33	.30	. 35	.27	. 26	. 29	.48	. 23	. 23
14.	Max Performance T/O	.37	.48	.42	.31	.34	.38	.46	.24	. 41	.34	.31	. 23
25.	Before Land Checks		.10	.12	.14	.20	.25	.38	.32	. 18	.16	.16	. 09
16.	Normal Approach	.10		. 64	.20	.37	.36	.46	.21	.46	.47	.37	.19
17.	Steep Approach	.12	.64		26	23	.34	.29	. 14	.41	.46	. 34	.02
8.	Shallow App Run Land	.14	, 20	. 26		.49	.50	.42	.11	. 33	.32	.14	. 24
9.	Hydraulic Failure	. 20	.37	. 23	.49		.55	.45	.31	.40	.39	.22	.45
0.	Antitorque Fail-L	. 25	. 36	.34	.50	.55		.69	.21	. 59	.54	.18	.45
1.	Antitorque Fail-R	.38	.46	.29	.42	.45	.69		. 28	. 55	.52	. 26	. 28
2.	Go-Arquind	.32	.21	.14	.11	.31	.21	.28		.14	. 16	.10	. 24
3.	Standard Auto	.18	.46	.41	. 33	.40	.59	.55	. 14		. 68	.15	. 10
4.	Low Level Auto	.16	.47	.46	. 32	. 39	.54	.52	. 16	.68		.14	. 20
6.	Decul/Accel	.16	.37	.34	.14	.22	. 18	. 76	.10	. 18	.14		. 21
7.	Eng Fail at Alt	.09	. 19	.02	. 24	.45	.13	. 28	. 24	.10	. 20	.24	~.
8.	High Reconnaissance	.12	.38	.37	. 33	. 29	. 24	.32	. 25	. 36	.30	.45	. 26
9.	Confined Area Opns	. 23	.25	. 29	. 36	. 29	. 28	.26	.16	. 28	.33	.37	.17
	Pin/Ridgeline Opns	.17	.34	.43	.40	.35	.50	.42	. 25	. 39	,43	.34	.07
١.	Ter Flight Plan	. 25	.28	.18	. 10	. 38	. 30	.24	. 42	. 23	.23	.41	. 39
	Ter Flight Nav	. 20	. 29	.27	. 1 2	.33	. 23	.24	.34	. 31	. 23	.21	. 28
	Low Level Flight	.41	.11	.08	.11	. 26	.31	. 26	,52	. 20	. 24	, 21	79
	NOE Flight	. 26	. 15	. 35	. 27	. 37	. 39	.33	.37	.53	. 45	.41	. 26
5.	ob Deceleration	.10	. 36	.23	.06	.47	.31	.20	,33	. 32	.34	.31	
	Ter Flight Approach	. 23	.31	.30	.17	. 26	. 24	.31	.31	. 41	.35		. 31
	OGE Check	. 27	.27	. 16	03	. 23	.12	.21		. 09	. 14	.27	. 29
	Ter Flight Takeoff	. 29	. 22	. 20				. 21	.29	. 09	. 14	.30	. 28

N = 78. Correlations greater than ,23 are significant at the .05 level. Those greater than ,30 are significant At the .01 level,

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	TASK	38	39	40	41	42	43	44	45	46	47	48
1.	Plan VFR Flight	.56	05	.07	.16	.14	.05	.06	.09	.11	02	.07
2.	Weight and Balance	04	.03	.15	01	. 12	01	.09	02	04	.02	.07
3.	Performance Charts	, 21	. 14	.13	.07	.31	03	.19	.06	.18	-,00	.11
4.	Prepare PPC	. 27	. 18	. 23	.11	. 26	.06	. 32	.05	.25	.04	.10
5.	Fuel Hanagement	. 17	. 05	.05	.04	.10	.04	.09	01	.05	.03	.08
6.	Preflight Inspect	.08	.10	.12	٠. 48	.31	.53	.33	. 26	,24	.30	.57
7.	Before T/O Checks	.05	.19	.08	.30	.02	.37	.16	.13	.07	.25	. 26
8.	Radio Procedure	.18	.21	. 10	.36	, 25	. 38	. 29	.17	.31	.36	.32
9.	After Land Tasks	.22	. 22	.35	.27	.11	.34	. 24	.19	.22	.19	. 28
10.	T/O to Hover	.21	. 15	. 15	.21	.11	.20	.15	. 39	.24	.21	.22
11.	Hover Check	.14	.31	. 06	.09	06	.15	.00	.18	.06	.06	.04
12.	Hovering Turn	. 18	. 17	, 20	.39	.25	. 26	.30	.51	.37	.36	.29
13.	Hovering Flight	. 24	. 24	. 19	.30	.14	.22	.22	. 35	.32	.42	.37
14.	Landing From Hover	. 19	. 23	.23	. 23	.18	.13	.18	.41	.24	.25	.15
15.	Manual Throttle Opn	. 30	. 36	, 45	. 24	.29	.23	, 35	.13	.20	.17	. 26
16.	Engine Fail Hover	.30	. 25	. 28	.32	.25	.21	.33	.41	.29	.17	.27
17.	Hovering Auto	.32	.33	.31	. 29	.35	.21	.39	. 33	.34	.17	. 27
18.	Slope Operations	.14	. 24	, 20	. 32	.25	.14	. 37	.41	.11	. 10	.16
19.	Truffic Pattern	.39	.30	.30	. 23	.16	.34	. 32	.28	.40	. 36	.27
20.	Climb/Descend	.25	.15	. 24	.32	.22	. 22	. 24	.37	.32	.27	.24
21.	Turns	.33	. 23	. 29	.42	.29	.36	.38	.40	.39	.27	.44
22.	Straight/Level Flt	.31	.40	. 37	. 30	.25	.40	.34	. 26	.39	.29	.44
23.	Normal Takeoff	.30	. 29	. 32	.42	.32	.35	.40	.22	.29	.37	.46
24.	Hex Performance T/O	.40	. 19	.40	. 27	.36	.31	.40	. 29	.41	.18	.46
25.	Before Land Checks	.12	. 23	.18	. 25	.20	.41	.26	.10	.23	.27	. 29
26.	Normal Approach	.38	. 25	. 34	. 28	. 29	.11	.35	. 36	.31	.27	.22
27.	Steep Approach	.37	. 29	.43	.18	.27	.08	.35	.23	.30	.16	.23
28.	Shallov App Run Land	3	.36	.40	.10	.12	.11	.22	.06	.17	03	. 25
29.	Hydraulic Failure	. 29	. 29	.35	. 38	.33	.26	. 39	.47	.26	.23	.33
30.	Antitorque Fail-L	, 24	. 28	.,50	.30	.23	.31	. 39	.31	,24	.12	. 38
31.	Antitorque Fail-R	.32	. 26	.42	. 24	. 24	.26	.33	, 20	.31	.21	. 26
32.	Go-Around	.25	.16	. 25	.42	.34	. 52	.37	. 22	.31	.29	. 29
33.	Standard Autp	.36	.28	.40	.23	.31	.20	.53	, 32	.41	.09	.27
	Low Level Auto	.30	.33	. 43	. 23	.23	.24	.45	. 34	.35	.14	.19
36.	Decel/Accel	. 45	.37	. 34	.41	.27	. 21	.41	.31	. 27	.30	. 36
37.	Eng Fail at Alt	. 26	. 17	.07	. 39	. 28	. 29	.26	.31	. 29	.28	. 37
38.	High Reconnaissance		.63	.41	. 39	.31	.45	.57	. 29	.66	.31	.47
39.	Confined Area Opns	.63		.61	. 26	.19	. 25	.42	. 25	.40	. 21	. 23
40.	Pin/Ridgeline Opns	.41	.61		. 17	.15	, 22	.41	. 22	. 36	.15	. 25
41.	Ter Flight Plan	. 39	. 26	.17		. 58	.69	.56	.41	.40	.49	.57
42.	Ter Flight Nav	.31	. 19	. 15	. 58	~-	.50	.46	. 18	.33	.36	.48
43.	Low Level Flight	.45	. 25	. 21	. 69	. 50		10	. 26	.52	.47	.65
44.	NOE Flight	.57	,42	.41	. 56	.46	.60		.48	.68	. 39	. 59
45.	NOE Deceleration	. 29	. 25	.22	.41	.18	. 26	.48		, 36	. 24	. 37
46.	Ter Flight Approach	.66	.40	.36	.40	. 32	. 52	.68	. 36		.47	. 59
47.	OGE Check	.31	. 21	. 15	. 49	. 36	. 47	.39	. 24	.47	4.5	.58
48.	Ter flight Takeoff	.47	. 23	.25	. 57	. 48	.65	. 59	. 37	.59	.58	

N = 78. Correlations greater than ,23 are significant at the .05 level. Those greater than ,30 are significant at the .01 level. 92Note. 86

APPENDIX I

MEANS, STANDARD DEVIATIONS, AND INTERCORRELATIONS
FOR CONFIDENCE RATINGS AND FINAL CHECKRIDE NORMALIZED SCORES

1. PLAN VFR Flight

	Variable	H	<u>50</u>	1	7)	4	5	6
Initi	al Checkride								
ι,	Pre-Confidence Rating	78.32	14.62						
	Checkride Score	41	. 96	.04					
3.	Post-Confidence Rating	81.75	13.53	.60**	.11				
Final	Checkride	•							
4.	Pre-Confidence Rating	75.41	16.50	.09	. 21*	.30**	~ ~		
	Checkride Score	. 02	. 95	.01	. 244	04	.02		
	Post-Confidence Rating	81.38	14.76	.32**	. 02	.5144	.66**	.02	

2. PREPARE WEIGHT AND BALANCE FORM

	Variable	Ħ	<u>\$D</u>	1	2	3	4	5	0
Initi	al Checkride	······································							
1.	Pre-Confidence Rating	53.03	26.66						
2.	Checkride Score	-1.51	. 89	.37**					
3.	Post-Confidence Rating	59.82	27.50	.74**	.47**				
Finel	Checkride								
4.	Pre-Confidence Rating	59.50	26.56	.42**	.37**	.37**			
5.	Checkride Score	67	1.38	01	.15	.05	.35**		
6.	Post-Confidence Rating	69.77	22.80	42**	.27*	.36**	.68**	.30**	

3. USE PERFORMANCE CHART

	Variable	Ħ	SD	1	2	3	4	5	6
Initi	al Checkride							· · · · · · · · · · · · · · · · · · ·	
ι.	Pre-Confidence Rating	66.05	20.96						
2.	Checkride Score	11	1.04	.19					
3.	Post-Confidence Rating	65.77	23.29	.76**	. 34**				
Final	Checkride								
4.	Pre-Confidence Rating	66.05	20.96	.38**	. 03	. 39**			
	Checkride Score	11	1.04	.08	. 15	. 23**	. 13		
6.	Post-Confidence Rating	65.77	23.19	.30**	.10	.42**	.76**	. 12	

4. PREPARE PERFORMANCE PLANNING CARD

	Variable	M	SD	1	2	3	4	5	6
Initi	al Checkride								
1.	Pre-Confidence Rating	64.03	22.71						
2.	Checkride Score	31	1.03	. 2 2					
3.	Post-Confidence Rating	66.34	22.57	.78**	. 36**				
Final	Checkride								
4.	Pre-Confidence Rating	65.73	23.16	.37**	.63	.39**			
5.	Checkride Score	. 35	.83	.07	.09	. 24	. 19		
	Post-Confidence Rating	72.50	21.31	.33**	. 09	.43**	.77**	. 28*	~ +

Note. Ap <.05; AAp < .01. Number of subjects = 75-78 except where noted otherwise.

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5. FUEL MANAGEMENT PROCEDURES

	Variable	М	<u>so</u>	ı	2	3	4	5	6
Initi	i Checkride		•	····					
1.	Pre-Confidence Rating	81.55	14.99						
2.	Checkride Score	.04	1.08	~.09					
3.	Post-Confidence Rating	80,50	17.96	,55**	.19				
Final	Checkride								
4.	Pre-Confidence Rating	79.56	15.43	.38**	.10	.50**	~=		
5.	Checkride Score	.30	1.02	.15	.11	. 18	.17		
6.	Post-Confidence Rating	79.65	15.19	. 274	. 23	,33**	.62**	. 26*	

6. PREPLIGHT INSPECTION

	Veriable	<u> </u>	SD	l	2	3	4	5	6
Initia	1 Checkride						•		
1.	Pre-Confidence Rating	78,56	17.56						
2.	Checkride Score	. 76	. 61	. 13					
3.	Post-Confidence Rating	82,72	15.25	,80**	.17	•=		•	
final	Checkride								
4.	Pre-Confidence Rating	78.12	16.40	. 34**	.14	.43**			
5.	Checkride Score	. 57	.40	05	18	03	10		
6.	Post-Confidence Rating	83.58	13.90	.3444	.03	.50**	.65** -	.08	

7. BEFORE TAKEOFF CHECKS

	Variable	Ħ	SD	ı	2	3	4	. 5	6
Initi	al Checkride								
ι.	Pre-Confidence Rating	82.07	14.77						
2.	Checkride Score	.80	. 50	.11					
3.	Post-Confidence Rating	83.17	13.90	.624#	.11				
Final	Checkride								
. 4.	Pre-Confidence Rating	80.51	14.03	.38**	.04	.41**			
5.	Checkride Score	. 32	.73	00	04	.02	.04		
6.	Post-Confidence Rating	82.96	14.95	.43**	03	.62*A	.6444	.11	

8. KADIO COMMUNICATIONS PROCEDURES

	Variable	<u>H</u>	<u>80</u>	l	2	3	4	5	6
Initi	1 Checkrida								
۱.	Pre-Confidence Rating	80.41	15.85	~-					
2.	Checkride Score	.54	.72	.08					
3.	Post-Confidence Rating	82.17	15.01	.57**	.00	•-			
Final	Checkride								
4.	Pre-Confidence Rating	77.49	16.74	.3144	.11	.4144			
5.	Checkride Score	.51	.51	02	. 02	.03	. 10		
6.	Post-Confidence Rating	82.77	13.03	. 3244	.11	.5444	.67**	. 09	

Note. *p < .05; **p < .01. Number of subjects * 75-78 except where noted otherwise.

9. AFTER LANDING TASKS

Variable	<u> </u>	<u>50</u>	1 2	3	4	5	6
Initial Checkride							
1. Pre-Confidence Rating	78. r.	16.71					
2. Checkride Score	.07	1.06	11				
 Post-Confidence Rating 	81.15	14.29	.60**05				
final Checkride							
4. Pre-Confidence Rating	78.42	15.64	.44**00	.58**			
5. Checkride Score	~.06	.70	.05 .36*	A .10	~.00		
6. Post-Confidence Rating	82.41	13.92	.49** .00	.58**	.76**	.14	

Keyete Kalasa Kasasa Keese Kees

10. TAKEOFF TO A HOVER

ı	Variable	Ñ	SD	1	2	3	4	5	6
Init	inl Checkride								
1.	Pre-Confidence Rating	84.51	14.17						
2.		. 26	.81	14					
3.	Post-Confidence Rating	.84	14.03	.65**	00		•		
Fina:	l Checkride								
4.	Pre-Confidence Rating	81.52	14.02	.37**	06	.50**			
5.	Checkride Score	. 28	. 56	04	.09	.06	. 25*		
6.	Post-Confidence Rating	83.96	12.61	.43**	.09	.61**	.74**	.09	-

11. HOVER CHECKS

	Variable	Ħ	<u>. SD</u>	ı	2	3	4	5	6
Initi	al Checkride								
ı.	Pre-Confidence Rating	81.56	16.11						
2.	Checkride Score	.19	. 85	08					
3.	Post-Confidence Rating	81.91	15.94	.63**	.08				
Final	Checkride								
4.	Pre-Confidence Rating	80.97	14.00	.36**	.01	.49**			
5.	Chackride Score	. 25	. 62	10	. 14	10	.02		
6,	Post-Confidence Rating	82.94	13.60	.36**	.06	.65**	.68**	.03	

12. HOVERING TURN

	Variable	W	<u>50</u>	l	2	3	4	5	b
Initi	al Checkride								
1.	Pre-Confidence Rating	83.76	14.04	••					
3.	Chackride Score Post-Confidence Rating	.47 81.18	.75 14.04	05 .68** -,	02				
Final	Checkride								
4.	Pre-Confidence Rating	81.27	13.36	.36**	09	.48**			
5.	Checkride Score	. 36	.43	05	18	04	. 15		
6.	Post-Confidence Rating	83.62	12.49	.50*	O2	.70**	, 7744	.09	

Note. Ap <.05; AAp <.01. Number of subjects = 75-78 except where noted otherwise.

13. HOVERING FLIGHT

	Vartable	<u> </u>	<u>so</u>	l	2 3	4	5	<u>, </u>
Initi	1 Checkride							
1.	Pre-Confidence Rating	83.82	13.94					
2.	Checkride Score	50	. 74	- .10 -	_			
3.	Post-Confidence Rating	83.36	13.80	.69** .14				
Final	Checkride							
4.	Pre-Confidence Rating	80.76	13.38	.42**0	6 .48**			
	Checkride Score	. 37	. 42	.122	2 .11	.09		
6.	Post-Confidence Rating	84.00	12.52	.49**0	6 .70**	.74**	. 05	

14. LANDING FROM A HOVER

	Variable	Ħ	<u>50</u>	1	2	3	4	5	6
Initi	al Checkride		·				*		
1.	Pre-Confidence Rating	81.87	15.79						
2.	Checkride Score	.18	.76	00					
3.	Post-Confidence Rating	81.42	15.56	.75**	.06				
Final	Checkride								
4.	Pre-Confidence Rating	79.32	14.66	.37**	00	.50**			
5.	Checkride Score	.27	. 53	.04	06	.03	. 12		
6.	Post-Confidence Rating	83.10	13.06	.41**	.00	.59**	.66**	.07	× •

15. MANUAL THROTTLE OPERATION

ENTERESTANCE PROPERTY FOR THE PARTY OF THE SECOND PROPERTY SECOND PROPERTY OF THE SECOND PR

	Variable	Н	<u>sb</u>	l	2	3	4	5	6
Initi	1 Chackridu		······································				····		-
1.	Pre-Confidence Rating	58.87	20.04						
2.	Checkride Score	57	.94	.31**					
3.	Post-Confidence Rating	66.97	23.36	.55**	. 35**				
Final	Checkride								
. 4.	Pre-Confidence Rating	59.82	20.20	.44**	.40**	.61**			
`5.	Checkride Score	67	.87	. 26*	.21	.05	. 23		
6.	Post-Confidence Rating	64.73	21.12	.36*	. 21	.45**	.65**	43**	

16. ENGINE FAILURE AT A HOVER

Variable	Ħ	SD	1	2	3	4	5	6
Initial Checkride			·	-				
 Pre-Confidence Rating 	76.77	17.82	÷~					
2. Checkride Score	. 21	.87	. 05					
 Post-Confidence Rating 	80.05	16.32	.68**	.10				
Final Checkride								
4. Pre-Confidence Rating	74.19	15.90	.44**	. 17	.5644			
5. Checkride Score	-,31	.81	. 20	.08	.22	.33**		
6. Post-Confidence Rating	81,45	14.96	.42**	. 06	. 66 **	.754#	264	

Note. *p <.05; **p <.01. Number of subjects = 75-78 except where noted otherwise.

17. HOVERING AUTOROTATION

	Variable	<u>м</u>	<u>\$</u> b	l	2		4	5	6
Initi	al Checkride								
ι.	Pre-Confidence Rating	76.82	16.75						
2.	Checkride Score	05	.88	. 11					
3.	Post-Confidence Rating	79.95	15.75	.69**	.18				
Final	Checkride		•						
4.	Pre-Confidence Rating	73.84	16.89	.42**	.26*	.49**			
5.	Checkride Score	05	. 74	.13	. 14	. 22	,28*		
6.	Post-Confidence Rating	81.28	15.13	.41**	.13	.60**	.78**	. 27 *	

18. SLOPE OPERATIONS

Variable	W	<u>5D</u>		2	3	4	5	6
Initial Checkride		····						~
1. Pre-Confidence Rating	69.26	18.01						
2. Checkride Score	11	.96	.06			•		
3. Post-Confidence Rating	75.96	17.84	.63** .	18				
Final Checkride								
4. Pre-Confidence Rating	70.15	18.36	.58** .	17	.53**			
5. Checkride Score	.01	.61	.24*	04	. 15	. 21		
6. Post-Confidence Rating	77.31	15.11	.41** .	05	.49~#	.7244	. 18	

19. TRAFFIC PATTERN

	Variable	<u>H</u>	<u>SD</u>	ı	2	3	4	5	6
Initia	ıl Checkride								
ι.	Pre-Confidence Rating	80.04	16.86						
2.	Checkride Score	03	. 86	10					
3.	Post-Confidence Rating	78.03	18.25	.63**	.02				
Final	Checkride								
4.	Pre-Confidence Rating	77.97	16.00	.52**	. 05	.60**			
	Checkride Score	. 25	. 58	05	03	.02	03		
	Post-Confidence Rating	80.47	15.74	.42**	.03	.69**	.65**	. 07	

20. CLIMB/DESCEND

Val	inble	Ä	<u>sd</u>	l	2	3	4	5	6
Initial Checks	ide							,	
I. Pre-Conf	idence Rating	83.38	13.88						
2. Checkrie		. 08	.77	11					
3. Pont -Cor	ifidence Rating	83.21	13.79	.67**	·· , 0 0	• **			
Final Checkris	le								
4. Pre-Conf	idence Rating	80.72	12.89	35 *	.04	.46**			
5. Checkrie	le Score	. 29	. 44	04	.02	02	02		
6. Post-Cor	ifidence Rating	82.11	12.84	. 36**	02	.66*	.69**	12	

Note, Apr. .05; AApr. .01. Number of subjects = 75-78 except where noted otherwise.

21. TURNS

	Variable	<u> </u>	<u>so</u>	1 .	2	3	4	5	6
Initi	al Checkride								
ı.	Pre-Confidence Rating	34.64	13.96						
2.	Checkride Score	.07	. 79	04					
3.	Post-Confidence Rating	82.59	14.82	.67**	.04				
Final	Checkride								
4.	Pre-Confidence Rating	81.18	15.85	.44**	. 05	.50**			
5.	Checkride Score	. 33	.54	10	. 284	.01	07		
6.	Post-Confidence Rating	82.91	13.23	.55**	.03	.68**	.79**	12	

22. STRAIGHT AND LEVEL FLIGHT



	Variable	Ħ	SD	1	2	3	. 4	5	6
Initi	al Checkride						•		
1.	Pre-Confidence Rating	85.38	14.01						
	Checkride Score	.34	. 78	.02					
3.	Post-Confidence Rating	83.44	14.81	.70**	05	. ••		•	
Final	Checkride								
4.	Pre-Confidence Rating	83.21	13.11	.47**	.16	.57**			
	Checkride Score	. 24	.61	.09	.05	.07	.06		
6.	Post-Confidence Rating	83.49	13.01	.52**	.12	.70**	.74**	.04	

23. NORHAL TAKEOFF

	Variable	H	SD	1	2	3	4	5	6
Initi	al Checkride								
2.	Pre-Confidence Rating Checkride Score Post-Confidence Rating	83.86 .09 83.41	13.38 .84 13.79	14 .67**	 11				
4. 5.	Checkride Pre-Confidence Rating Checkride Score Post-Confidence Rating	80.10 .21 82.92	13.46 .62 12.71	.37** .13 .39**	05	.49** .20 .70**	.22	.24*	•

24. MAXIMUM PERFORMANCE TAKEOFF

Variable	Ħ	SD	ı	2	3	4	5	6
Initial Checkride								
1. Pre-Confidence Rating	78.99	15.36					24	
2. Checkride Score	30	. 87	.12					
3. Post-Confidence Rating	80.63	15.30	.69**	. 07		5		
Final Checkride								
4. Pre-Confidence Rating	77.22	15.54	35 mm	.06	48**			
5. Checkride Score	. 11	. 76		00	.23	.18		
6. Post-Confidence Rating	79.97	15.05	31,44	. 23	.59**	57**	. i 5	

Note. *p< .05; **p < .01. Number of subjects * 75-78 except where noted otherwise.

25. BEFORE LANDING CHECKS

	Variable	Ħ	<u>50</u>	1	2	3	4	5.	. 6
Initi	ol Checkride					•			
۱.	Pre-Confidence Rating	83.84	15.03						
2.	Checkride Score	.02	1.05	13				-	•
3.	Post-Confidence Rating	82.69	14.24	.71**	.08	••			
Final	Checkride							50 To 1	
	Pre-Confidence Rating	82.06	13.40	.41**	.01	.53**			
5.	Checkride Score	06	.85	.11	.06	.17	.274		
6.	Post-Confidence Rating	82.93	15.28	.50**	.03	.65**	.72**	.21	

26. MORMAL APPROACH

LIGHT CONTRACTOR OF THE PROPERTY OF THE PROPER

	Variable	<u>H</u>	SD	1	2	3	4	5	6
Inicia	al Checkride								
1.	Pre-Confidence Rating	79.18	16.56				_		
2.	Checkride Score	09	.89	13			- T		1.47
3.	Post-Confidence Rating	78.95	17.53	.70**	.02				
Final	Checkride						100	. •	
4.	Pre-Confidence Rating	78.52	15.01	.44**	.06	.53**		e e	
5.	Checkride Score	.07	.65	.11	.11	. 17	.23		
6.	Post-Confidence Rating	81.03	14.43	.43**	.11	.65**	.69**	.21	

27. STEEP APPROACH

	Veriable	Ħ	<u>SD</u>	ı	2	3	4	5	-6
Initi.	al Checkride								
ı.	Pre-Confidence Rating	78.99	15.89						
2.	Checkride Score	28	.81	.06					
3.	Post-Confidence Rating	77.75	18.20	.71**	.02				
Final	Checkride							4	
4.	Pre-Confidence Rating	77.71	14.86	.40**	03	.47**			
5.	Checkride Score	15	.66	.03	.00	.09	.06		
, 6.	Post-Confidence Rating	79.10	14.68	37**	01	.5144	.60**	.17	

28. SHALLOW APPROACH TO A RUNNING LANDING

	· Variable	H.	<u>SD</u>	1	2	3	4	5	6
Initi	al Checkride								
1.	Pre-Confidence Rating	78.77	16.10						
2.	Checkride Scote	07	. 94	.14					
3.	Post-Confidence Rating	79.67	17.47	.65**	.15			-	
Fin-l	Checkride					e '	4 7	°C	\$ **
4.	Pre-Confidence Rating	77.04	15.75	.42**	.02	.55**			
5.	Checkride Score	.16	. 76	15	.10	.05	. 18		
6.	Post-Confidence Rating	80.62	14.80	. 37**	.07	.66**	.72**	.16	

Note. #p< 05; ##p< .01. Number of subjects = 75-78 except where noted otherwise.

29. HYDRAULICS FAILURE

	Variable	Щ	<u> 50</u>	1	3	3	4	3	tı
Initi	al Checkride	· ···········							
1.	Pre-Confidence Rating	74.50	16.70						
2.	Checkride Score	35	. 94	. 07					
3.	Post-Confidence Rating	77.97	16.43	.63**	.29*				
Finel	Checkride								
4.	Fra-Confidence Rating	72.85	16.64	.4344	.01	. 50**			
	Checkride Score	41	. 96	.00	.16	. 05	.09		
6.	Post-Confidence Rating	79.10	14.60	.3[**	06	60**	.65**	. 11	

30. ANTITORQUE PAILURE--LEFT PEDAL

	N 4 - 1 N -			•					
	Variable	Ħ.	<u>5D</u>	1	<u> </u>		4		6
Initia	al Checkride								
١.	Pre-Confidence Rating	61.26	20.08						
2.	Checkride Score	-1.15	1.07	. 12					
3.	Post-Confidence Rating	64.73	22.62	.65**	.264				
Final	Checkride								
4.	Pre-Confidence Rating	59.41	20,56	.39**	.12	.58**			
5.	Checkride Score	78	1.02	.30**	.39**	. 23	. 23	~	
6.	Post-Confidence Rating	68.90	19.19	.39**	.02	.58**	.67**	.33**	

31. ANTITORQUE FAILURE--RIGHT PEDAL

,	Variable	<u> </u>	SD	1	2	3	4	3	6
initi	al Checkride								
1.	Pre-Confidence Rating	61.26	20.08						
2.	Checkride Score	-1.12	1.05	.23					
3.	Post-Confidence Rating	64.73	22.62	.65**	.47**				
Final	Checkride								
4.	Pre-Confidence Rating	59.41	20.56	.39**	.20	.57**			
5.	Checkride Score	85	. 97	. 20	.23	.25*	.28*		
6.	Post-Confidence Rating	68.90	19.19	39**	. 19	.58**	.67**	.4444	

32. GO-AROUND

	Variable	<u>H</u>	SD	ı	2	3	4	5	ь
Initi	al Checkride								
1.	Pre-Confidence Rating	81.31	16.26						
	Checkride Score	. 20	. 78	05					
3.	Post-Confidence Rating	8C.08	16.79	54**	07				
Final	Checkride								
4.	Pre-Confidence Rating	79.68	14.76	44*	.03	. 46##			
5.	Checkride Score	. 34	.47	03	, Do	.04	0 /		
ь.	Post-Confidence Asting	81.94	15.83	4340	.11	.50**	7 e) n n	. 25 *	

Note: *p: .05; **p: .01. Number of subjects * 75-78 except where noted otherwise.

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33. STANDARD AUTOROTATION

	Variable	M	<u>SD</u>	1	2	3	4	ל	h
Initi	al Checkride								
1.	Pre-Confidence Rating	74.20	18.85						
2.	Checkride Score	84	.97	.09					
1.	Post-Confidence Rating	74.11	20.92	.61**	.39**				
Final	Checkride								
4.	Pre-Confidence Rating	71.14	19.08	.52**	.19	.53**			
5.	Checkride Score	62	.98	. 30*	.14	. 23	. 20		
6.	Post-Confidence Rating	77.45	16.28	.45**	. 27	.57**	.73**	. 33*	

34. LOW LEVEL AUTOROTATION

	Variabla	М	<u>SD</u>	l	2	3	4	5	6
Initi	al Checkride								
1.	Pre-Confidence Rating	73.15	18.86						
2.	Checkride Score	~.80	.81	. 15			•		
3.	Post-Confidence Rating	72.73	20.90	.58**	. 22				
Final	Checkride							•	
4.	Pre-Confidence Rating	69.99	18.48	.49**	.07	.50**			
5.	Checkride Score	53	.93	.20	. 23	. 27*	.30**		
6.	Post-Confidence Rating	75.99	17.72	.49**	.13	.57**	.72**	.34**	

36. DECELERATION/ACCELERATION

	Variable	<u> </u>	<u>SD</u>	1	2	3	4	5	6
Initi	al Checkride								
1.	Pre-Confidence Rating	79.79	14.51						
2.	Checkride Score	.16	, 85	.06					
3.	Post-Confidence Rating	79.58	15.75	.48**	.07				
Final	Checkride								
4.	Pre-Confidence Rating	77.62	15.64	.41**	.09	.4144			
5.	Checkride Score	.17	.73	04	.18	. 04	.17		
6.	Post-Confidence Rating	79.45	14.69	. 34**	12	.56**	.73**	. 254	

37. ENGINE FAILURE AT ALTITUDE

	Variable	<u> </u>	<u>su</u>		2	3	4	5	· ·
Initia	al Checkride								
1.	Pre-Confidence Rating	73.50	18.16						
2.	Checkride Score	05	1.05	. 14					
3.	Post-Confidence Rating	85.83	17.67	.71**	, 10				
Final	Checkride								
4.	Pre-Confidence Rating	70.92	18.10	.59**	.17	.65**			
5.	Checkride Score	.10	. 76	. 1.1	.17	.13	. 1 3		
6.	Post-Contidence Rating	76.99	17.56	. 5 3 * *	04	. 70+≜	* * + B .	, lb	

Note: *p < 05; **p < .01 Number of subjects = 75-78 except where noted otherwise

JA. HIGH RECONNAISSANCE

	Variable	<u>H</u>	<u>şb</u>	l	2	1	4	ĵ	h
Initia	nl Checkride		***************************************						
1.	Pre-Confidence Rating	71.30	17.67						
2.	Checkride Score	. 06	' .85	12					
3.	Post-Confidence Rating	73.44	16.49	.58**	-,0)				
Final	Checkride								
4.	Pre-Confidence Rating	73.44	16.49	.46**	06	.44**			
	Checkride Score	.43	.53	.08	09	. 18	.12		
6.	Post-Contidence Rating	79.09	15.29	.44**	01	.59**	.82**	.24*	-

39. CONFINED AREA OPERATIONS

	Variable	<u>H</u>	<u>SD</u>	ı	2	3	4	5	ь
initi	al Chackride						• -	·	
۱.	Pre-Confidence Rating	74.63	16.48						
2.	Checkride Score	12	.89	06	~-				
3.	Post-Confidence Rating	77.05	15.99	.63**	.03				•
Final	Checkride								
4.	Pre-Confidence Rating	73.50	15.47	.45**	.04	.44**			
5.	Checkride Score	. 23	.59	.11	.01	. 26	. 14	P) ==	
6.	Post-Confidence Rating	79.35	14.73	.42**	.04	. \$6**	.76**	.31*a	

40. PINNACLE/RIDGELINE OPERATIONS

		Variable	Ħ	SD	l	2	3	4	5	f.
•	Inici	al Checkride								
	١.	Pre-Confidence Rating	71.88	17.47						
	2.	Chackride Score	.00	. 95	16					
	3.	Post-Confidence Rating	76.45	16.18	.63**	.03				
	Final	Checkride								
	4.	Pre-Confidence Hating	72.19	15.44	.46**	. 13	.49**			
٠	5.	Checkride Score	.04	.72	.12	13	.11	. 23		
	6.	Post-Confidence Rating	78.42	15.24	.36**	.01	.50**	7144	.31**	

41. TERRAIN FLIGHT MISSION PLANNING

	Variable	<u>M</u>	<u>sv</u>	1 2	3	4	5	11
Initi	al Checkride	*						
1.	Pre-Confidence Rating	u/.69	18.71					
2.	Checkride Score	.17	.83	10				
3.	Post-Confidence Rating	45 05	18.80	.73**1H				
Final	Checkride							
4	Pre-Confidence Kating	69.6	18.56	.32**01				
۶.	Checkride Score	.51	.40	-,04 01	10	0;		
€1.	Post-Confidence Rating	77 38	15.04	.3144 ite	.48**	. 3 * *	; •	

Note: *p.:05; **p.:01. Number of subjects > 75-78 except where cored otherwise

42. TERRAIN FLIGHT NAVIGATION

Variable	Щ	<u>st)</u>	l		3	4	5	h
al Checkride								
Pre-Confidence Rating	70.06	17.97						•
Checkride Score	.01	1.00	17					
Post-Confidence Rating	75.87	16.82	.77**	01				
Checkride		•						
Pre-Confidence Rating	71.60	17.64	,42**	10	.45**			
Checkride Score	. 34	.74	. 15	00	. 18	. 04		
Post-Confidence Rating	78.91	15.45	,4044	25**	.52**	.76**	.27**	
	al Checkride Pre-Confidence Rating Checkride Score Post-Confidence Rating Checkride Pre-Confidence Rating Checkride	al Checkride Pre-Confidence Rating 70.06 Checkride Score .01 Post-Confidence Rating 75.87 Checkride Pre-Confidence Rating 71.60 Checkride Score .34	al Checkride Pre-Confidence Rating 70.06 17.97 Checkride Score .01 1.00 Post-Confidence Rating 75.87 16.82 Checkride Pre-Confidence Rating 71.60 17.64 Checkride Score .34 .74	Al Checkride Pre-Confidence Rating 70.06 17.97 Checkride Score .01 1.0017 Post-Confidence Rating 75.87 16.82 .77** Checkride Pre-Confidence Rating 71.60 17.64 .42** Checkride Score .34 .74 .15	Al Checkride Pre-Confidence Rating 70.06 17.97 Checkride Score .01 1.0017 Post-Confidence Rating 75.87 16.82 .77**01 Checkride Pre-Confidence Rating 71.60 17.64 .42**10 Checkride Score .34 .74 .1500	Variable M SD i 3 a1 Checkride Pre-Confidence Rating 70.06 17.97 Checkride Score .01 1.00 17 Post-Confidence Rating 75.87 16.82 .77**01 Checkride Pre-Confidence Rating 71.60 17.64 .42**10 .45** Checkride Score .34 .74 .15 00 .18	Variable M SD i / i / i 4 al Checkride Pre-Confidence Rating 70.06 i7.9/ Checkride Score .01 1.0017 Post-Confidence Rating 75.87 16.82 .77**01 Checkride Pre-Confidence Rating 71.60 17.64 .42**10 .45** Checkride Score .34 .74 .1500 .18 .04	Al Checkride Pre-Confidence Rating 70.06 17.97 Checkride Score .01 1.0017 Post-Confidence Rating 75.87 16.82 .77**01 Checkride Pre-Confidence Rating 71.60 17.64 .42**10 .45** Checkride Score .34 .74 .1500 .18 .04

43. LOW-LEVEL FLIGHT

Variable	M	<u>s</u> d	ı	2	3	4	5	l;
Initial Checkride			· · · · · · · · · · · · · · · · · · ·		 			
l. "re-Confidence Rating	75.82	16.22						
2. Checkride Score	. 32	.77	15			•		
3. Post-Confidence Rating	79.58	15.77	.79**	. 1 2				
Final Checkride							į	
4. Pre-Confidence Rating	75.99	16.35	.39** .	.03	.55**			
5. Checkride Score	.47	.51	.06	17	.18	. 12		
6. Post-Confidence Rating	80.90	13.91	.39**	. 18	.59**	,73**	. 26 *	
								_

44. NOE FLIGHT

	Variable	Ħ	SD	1	2	3	4	5	6
Initia	1 Checkride	 				- 			
1.	Pre-Confidence Rating	15.14	19.04						
2.	Checkride Score	.25	.80	24*					
3.	Post-Confidence Rating	78.16	17.05	.75**	15				
Final	Checkride								
4.	Pre-Confidence Rating	73.59	16.92	.47**	08	.54**			
5.	Checkride Score	.41	.60	.07	12	. 08	.11		
6.	Post-Confidence Rating	80.91	13.53	.36**	10	.58**	.73**	. 26*	

45. NOE DECELERATION

Variable	M	<u>50</u>	1	2	3	4	5	<u></u>
Initial Checkride								
1. Pre-Confidence Rating	68.99	19.97						
2. Checkride Score	~.27	. 84	OH	٠.				
Post-Confidence Rating	72.50	20.11	.74**	.42				
Final Checkride								
4. Pre-Confidence Rating	68.88	14.14	.44**	. 14	. 52**			
5. Checkride Score	~,04	.86	. 1 3	. Ut	. 15	.02		
6. Post-Confidence Rating	75.50	18.42	. 33**	.28*	.68**	.62**	. 15	

Note: Apr. 35; AApr. 301. Number of subsects * 75-78 except where noted otherwise.

46. TERRAIN FLIGHT APPROACH

	Variable	М	SD	1	2	3	4	5	6
init i	al Checkride			·				· — — · · · · · · · · · · · · · · · · ·	
1.	Pre-Confidence Rating	70.74	19.23						
2.	Checkride Score	.07	89	06					
3,	Post-Confidence Rating	76.95	17.25	.70**	04				
final	Checkride								
4.	Pre-Confidence Rating	73.10	17.45	.36**	. 04	.47**			
	Checkride Score	.45	.50	.12	00	. 24 *	. 26*		
6.	Post-Confidence Rating	80.30	14.75	.27*	09	. 52**	.72**	.33**	

47. OUT-OF-GROUND EFFECT CHECK

Variable	Ħ	<u>\$D</u>	l l	2	3	4	5	6
Initial Checkride								
1. Pre-Confidence Rating	71.64	18.72						
2. Checkride Score	40	. 98	.02					
3. Post-Confidence Rating	74.04	17.66	.62**	.03				
Final Checkride								
4. Pre-Confidence Rating	73.60	17.27	,39**	.13	.33**			
5. Checkride Score	.09	.85	06	.06	07	.18		
6. Post-Confidence Rating	78.19	17.20	.32**	08	.51**	.69**	.19	

48. TERRAIN FLIGHT TAKEOFF

Variable	<u>м</u>	<u>50</u>	1	2	. 3	4	5	6
Initial Checkride								
1. Pre-Confidence Rating	74.21	18.80						
2. Checkride Score	05	.81	11					
 Post-Confidence Rating 	79.21	14.74	.61**	10				
Final Checkride								
4. Pre-Confidence Rating	75.61	15.65	. 274	.08	.48**			
5. Checkride Score	. 32	. 65	. 07	. 28*	.01	. 10		
6. Post-Confidence Rating	80.86	14.86	. 27 4	03	.6244	.72**	. 08	

Note: *p < .05; **p' .01. Number of subjects = 75-78 except where noted otherwise.